



# Algorithms and Data Structures

## Data Types

Ulf Leser

# Content of this Lecture

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- Example
- Abstract Data Types
- Lists, Stacks, and Queues
- Realization in Java

# Problem

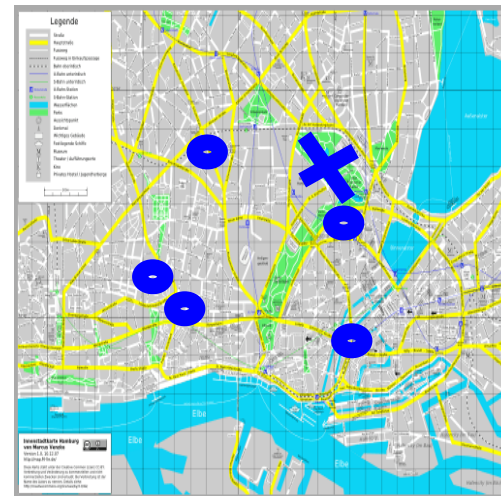
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- Suppose you are in the centre of Hamburg and are **looking for the next (i.e., closest)** laptop repair shop
- Fortunately, your mobile knows your position and has a list of laptop repair shops in Hamburg
- How does your mobile find the **closest shop**?

# Classical Post Box Problem

- Suppose a city with  $n$  boxes located at arbitrary positions
- You wake up in the middle of the city with a letter in your hand; the letter should be thrown in the closest post box
- How do you find the closest post box?
  - You have a list with locations of all post boxes
- Looking at a map is not the answer
- Devise an algorithm

```
S: set_of_coordinates;  
c: coordinate (x,y)  
...
```



# Simple Solution

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- How much work?

```
Input
  S: set_of_coordinates;
  c: coordinate (x,y);    # your loc
t: coordinate;           # closest box
m: real := MAXREAL;      # smal. dist
for each c'∈S do
  if m > distance(c,c') then
    m := distance(c,c');
    t := c';
  end if;
end for;
return t;
```

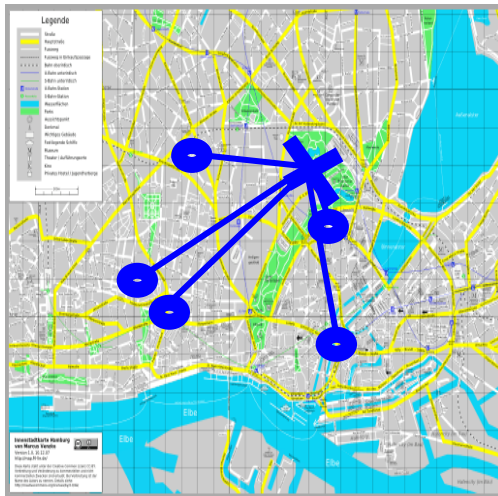
# Simple Solution

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Input
  S: set_of_coordinates;
  c: coordinate (x,y);      # your loc
t: coordinate;              # closest box
m: real := MAXREAL;        # smal. dist
for each c'∈S do
  if m > distance(c,c') then
    m := distance(c,c');
    t := c';
  end if;
end for;
return t;
```

- Clearly, we can save the second call to “distance”
- Thus, we need to compute  $|S|$  distances, make  $|S|$  comparisons, and perform at most  $2 \cdot |S|$  assignments
- We perform  $O(|S|)$  operations, which are  $O(1)$  or distance computations

# Simple Solution



- How much work?
- Clearly, we can save the second call to “distance”
- Thus, we need to compute  $|S|$  distances, make  $|S|$  comparisons, and perform at most  $2 * |S|$  assignments
- **Euclidian distance**
  - 6 arithmetic ops per distance

$$\text{dist}((x_1, y_1), (x_2, y_2)) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

# Not the only Option



- How much work?
- Clearly, we can save the second call to “distance”
- Thus, we need to compute  $|S|$  distances, make  $|S|$  comparisons, and perform at most  $2 * |S|$  assignments
- **Manhattan distance**
  - 5 operations, and different ones

$$\text{dist}((x_1, y_1), (x_2, y_2)) = |x_1 - x_2| + |y_1 - y_2|$$



# Complexity



- How much work?
- Clearly, we can save the second call to “distance”
- Thus, we need to compute  $|S|$  distances, make  $|S|$  comparisons, and perform at most  $2 * |S|$  assignments
- Both cases:  $O(|S| * \text{dim}(S))$ 
  - $\text{dim}(S)$ : Number of dimensions of every point in  $S$

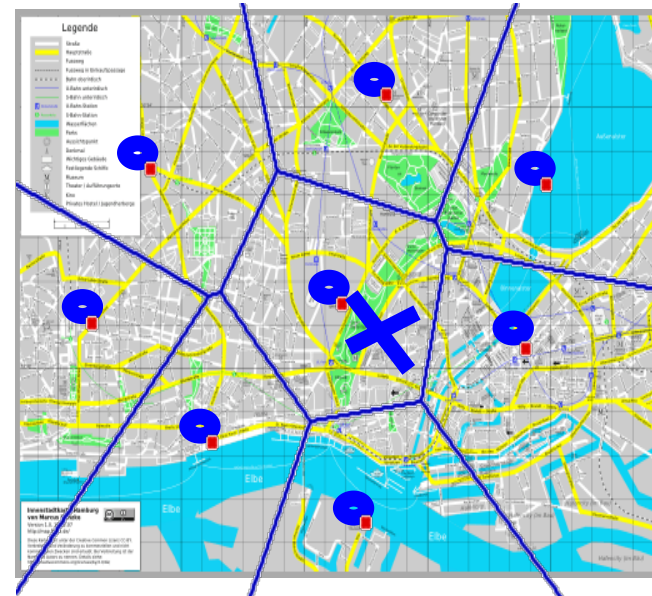
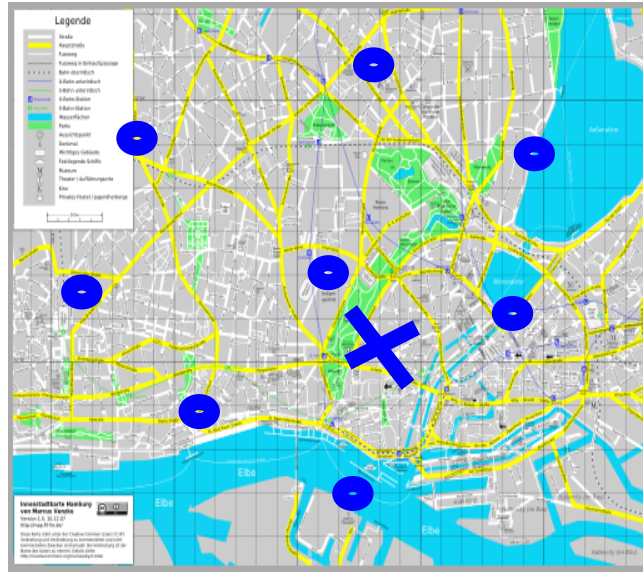
# Data Structure Point of View

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```
input
  S: set_of_coordinates;
  c: coordinate (x,y);
t: coordinate;
m: real := MAXREAL;
For each c' ∈ S do
  if m > dist(c,c') then
    m := dist(c,c');
    t := c';
  end if;
end for;
return t;
```

- Data structures
  - We need a list of coordinates
  - The algorithm must iterate over the elements of this list
  - A **linked list** would suffice
- Now assume we need to perform such **searches very often**
  - Can we represent S in **another way (S')**, such that searching requires less work?
  - Note: Time for **computing S' from S will be ignored**
    - Performed before searching starts
    - Assuming that S does not change

# Voronoi Diagrams



- **Pre-processing**: Compute for every point  $s \in S$  its **Voronoi area**, i.e., the area in which all points have  $s$  as **nearest point** from  $S$
- Can be achieved in  $O(|S| \cdot \log(|S|))$  time (no details here)
- Nearest-neighbor search using Voronoi diagrams is  $O(\log(|S|))$
- Conclusion: Finding a **proper data structure** does pay off

# More Abstract

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- We want a **piece of software T** that
  - can store a list of coordinates
  - can compute the nearest point to a given point  $c$
  - Piece of software: (1) algorithm and (2) data structure
- Thus, T must support (at least) two **operations**
  - `T.init(S: list_of_coordinates)`
  - `T.nearestNeighbor(c: coordinate): coordinate`
  - T apparently uses **another data structure**: “coordinate”
- Such combinations of **object sets and operations** on these sets are called a **data type**
- If only look at sets and operations: **Abstract data type**
  - No details on algorithms / implementation

# Content of this Lecture

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- Example
- **Abstract Data Types**
- Lists, Stacks, and Queues
- Realization in Java

# Abstract Data Types (ADT)

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- An ADT defines a **set of operations** over a **set of objects** of a certain (more basic) type
  - Or over **multiple sets** of objects of different or same types
- The set of operations and types is called **signature**
- An ADT is **independent of an implementation**
  - Different data structures to represent the objects
  - Different algorithms to implement the operations
  - An ADT is independent of any programming language
- **Encapsulation**: Objects are accessed only through the ops
- An implementation of a ADT is called a **concrete (or physical) data type**

# Example

---

```
type points
import
  coordinate;
operators
  add:      points x coordinate → points;
  neighbor: points x coordinate → coordinate;
```

- ADT that we could use for our app for searching shops
- We only need **two operations**
  - A way to insert shops (with their coordinates)
  - A way to get the nearest shop with respect to a given coordinate
- We assume basic data types to be given (string, int ...)
- Not the only way ...

# Modeling More Details

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```
type shop
import
  coordinate;
  string;
operators
  getName: shop → string;
  getCoor: shop → coordinate;
```

```
type shops
import
  shop;
operators
  add: shops x shop → shops;
  neighborC: shops x coordinate → coordinate;
  neighborN: shops x coordinate → string;
  neighborS: shops x coordinate → shop;
```

- An ADT defines **what is necessary**
- Designing a ADT is a **modeling process**
  - Shop owner? Laptop models being repaired? Opening hours?
  - Depends on requirements, ease-of-use, extensibility, personal preferences, existing ADTs, ...



# Reusing Existing ADTs

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- For implementing points (or shops), it would be helpful to import something that can hold a set of coordinates
- We **need a list** – an ADT in itself
  - A **parameterized ADT** – a list of elements of an arbitrary ADT T
  - For our ADT **points**, T will use objects of type **coordinate**

```
type list( T)
import
  integer, bool;
operators
  isEmpty: list → bool;
  add:     list x T → list;
  delete:  list x T → list;
  contains: list x T → bool;
  length:  list → integer;
```

# Axioms: What we Know about an ADT

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- We expect operations on lists to have a **certain semantic**
  - Adding an element increases length by one
    - If we assume **bag semantics**
  - Deleting an element that doesn't exist creates an error
  - If a list is empty, its length is 0
  - ...

```
type list( T)
import
  integer, bool;
operators
  isEmpty: list → bool;
  add:     list x T → list;
  contains: list x T → bool;
  delete:  list x T → list;
  length:  list → integer;
axioms: ∀ l: list, ∀ t: T
  length( add(l, t)) = length( l) + 1;
  length( l)=0 ⇔ isEmpty(l);
  ...
```

# List versus Points

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```
type points
import
  coordinate, bool, list( coordinate);
Operators
contains: points x coordinate → bool;
  # Implement as list.contains
add:      points x coordinate → points;
  # Implement as list.add
neighbor: points x coordinate → coordinate;
  # Not implemented in list!
axioms
neighbor(p,c) = {x | contains(p,x) ∧ ∀x':contains(p, x')=>
  distance(x,c) ≤ distance(x',c)};
```

- `points` uses a list and adds further functionality
- What's wrong?
  - What happens if **multiple x have the same distance** to c?

# List versus Points

---

```
type points
import
  coordinate, bool, 2Dspace;
Operators
  contains: points x coordinate → bool;
  add:      points x coordinate → points;
  neighbor: points x coordinate → points;
axioms
  neighbor(p,c) = {x | contains(p,x) ∧ ∀x': contains(p,x'):
                    distance(x,c) ≤ distance(x',c)};
```

# Content of this Lecture

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- Data Structures Again
- Abstract Data Types
- Example: Lists, Stacks, and Queues
  - Parameterized ADTs
- Realization in Java

# Lists, Stacks, Queues

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- We looked at a data type (points, shops) which essentially is a list with one **special operation**: nearestNeighbor
  - Canonical list operations: insert, search, delete, update, length
- There are many ways to implement the **general ADT list**
  - Array, linked lists, double-linked lists, trees, ...
- Two types of lists are of exceptional importance in computer science: **Stacks and Queues**
  - Both support mostly two operations
  - These suffice for surprisingly many problems and applications
  - Can be **implemented very efficiently**

# Queues

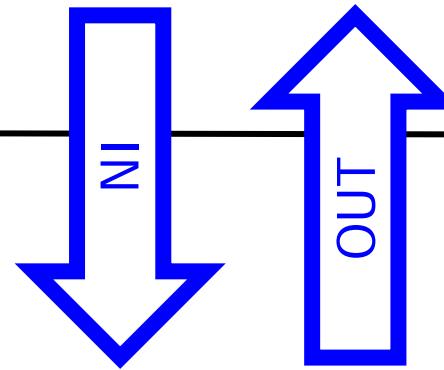
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- Operations: enqueue, dequeue
- Special semantic: First in, first out (FIFO)
- Breadth-first traversal, shortest paths, BucketSort, ...

# Stacks

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- Operations: push, pop
- Special semantic: Last in, first out (LIFO)
- Call stacks, backtracking, "Kellerautomaten", ...



# As Abstract Data Types

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```
type stack( T)
import
  bool;
operators
  isEmpty: stack → bool;
  push:    stack x T → stack;
  pop:     stack → stack;
  top:     stack → T;
```

```
type queue( T)
import
  bool;
operators
  isEmpty: queue → bool;
  enqueue: queue x T → queue;
  dequeue: queue → queue;
  head:    queue → T;
```

- Where's the [difference](#)?

# Signature does not Suffice

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```
type a( T)
import
  bool;
operators
  isEmpty: a → bool;
  add:    a x T → a;
  remove: a → a;
  give:   a → T;
```

```
type a( T)
import
  bool;
operators
  isEmpty: a → bool;
  add:    a x T → a;
  remove: a → a;
  give:   a → T;
```

- Where's the difference?
- From the **signature alone**, there is no difference
- Yet – we expect a **different behavior**

# Defining the Difference

---

```
type stack( T)
import
  bool;
operators
  isEmpty: stack → bool;
  push:    stack x T → stack;
  pop:     stack → stack;
  top:     stack → T;
axioms ∀ q:stack, ∀ t:T
  top( push( s, t)) = t;
  pop( push( s, t)) = s;
```

```
type queue( T)
import
  bool;
operators
  isEmpty: queue → bool;
  enqueue: queue x T → queue;
  dequeue: queue → queue;
  head:    queue → T;
axioms ∀ q:queue, ∀ t:T
  head( enqueue( q, t)) =
    if isEmpty( q): t
    else head( q);
  dequeue( enqueue( q, t)) =
    if isEmpty( q): q
    else enqueue( dequeue( q), t);
```

Long version:

$\text{push}(s, t) \circ \text{top}(s) = t' \Rightarrow t = t'$

$\text{push}(s, t) \circ \text{pop}(s) = s' \Rightarrow s = s'$

# Example

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```
type queue( T)
...
dequeue( enqueue( q, t)) =
  if isEmpty( q): q
  else enqueue( dequeue(q), t);
```

```
d( e( <3,2>, 5)) = e( d( <3,2>), 5) =
  e( d( e( <3>, 2)), 5) =
  e( e( d( <3>), 2), 5) =
  e( e( d( e(<>), 3), 2), 5) =
  e( e( <>, 2), 5) =
  <2,5>
```

# We Stop Here

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- There are various ways to **formally specify the behavior** of operations of an ADT
- For instance: Algebraic specifications
  - Define an algebra over the object sets of the ADT
  - Includes axioms defining the **semantics of operations**
  - Axioms are essential to **prove aspects** of a system's behavior
    - Ideally, one only specifies and never programs
  - See lecture on "Modellierung und Spezifikation"
- In this lecture, we only look at **signatures**
  - No axioms
  - Supported by **most programming languages** (e.g. Java interfaces)

# Content of this Lecture

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- Data Structures Again
- Abstract Data Types
- Lists, Stacks, and Queues
- **Realization in Java**

# ADTs in Java

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- Recall
  - An ADT summarizes the **essential operations** on a **set of objects**
  - An ADT is **independent of a realization**/implementation
  - Any implementation of a ADT is called a **concrete data type**
- Realization in Java?
- **Interfaces**
  - Only exhibit the essential operations on a class of objects
  - Can have different implementations
  - Can be implemented by a concrete class

# Remarks

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- Java **does not support axioms** on interfaces
  - Some other languages do, e.g. contracts in Eiffel
- Java adds important functionality for practical work which we ignore in this lecture
  - **Inheritance**, visibility (public, protected, ...), overloading, ...
  - Critical: **Encapsulation** – you must not see anything of an object / do anything with an object that is not represented in its interface
  - See lectures on Software Engineering
- Historically, **ADTs are a predecessor** of classes in programming languages



# Summary

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- ADT's specify the possible **operations** on a data structure
- ADT's are **free of implementation** details
- We often discuss pros/contras of **different ways to implement** a given ADT
- We will often assume certain data types to be given
  - Always: Strings, integers, reals, ...
  - We make implicit assumptions on cost of operations: UCM
- (Formal) ADTs can be used for much more
  - Proving properties of a data type
  - Proving that a concrete data type implements a ADT
  - Proving that an implementation does not hurt axioms
  - **Program verification**

# Exemplary Questions

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- What is an abstract data type, what is a physical data type?
- What are typical operations of a list? Of a stack?
- Imagine a class storing rectangles in a plane. We want to add and remove rectangles, test if there are any rectangles, and find all rectangles intersection of given one. Define the ADT. What could be possible axioms?