

## Algorithms and Data Structures

Amortized Analysis

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- Two Examples
- Two Analysis Methods
- Dynamic Tables
- SOL - Analysis
- This lecture is not covered in [OW93] but, for instance, in [Cor03]


## Setting

- SOL: Sequences of operations influencing each other
- We have a sequence $Q$ of operations on a data structure
- Searching SOL and rearranging a SOL
- Operations are not independent - by changing the data structure, costs of subsequent operations are influenced
- Conventional WC-analysis produces misleading results
- Assumes all operations to be independent
- Changing search order in a workload does not influence WC result
- Amortized analysis analyzes the complexity of any sequence of dependent operations
- In other terms: We seek the worst average cost of each operation in any sequence


## „Amortizing"

- Economics: How long does it take until a (high) initial investment pays off because it leads to continuous business improvements (less costs, more revenue)?
- Example:
- Investment of $6000 €$ leads to daily rev. increase from 500 to $560 €$
- Investment is amortized after 100 days
- WC: Look at all days independently
- Look at ratio cost / revenue
- Compare 560-6000 to 500-0
- Don't invest!



## Algorithmic Example 1: Multi-Pop

- Assume a stack $S$ with a special operation: $\operatorname{mpop}(k)$
- mpop(k) pops min(k, |S|) elements from S
- Implementation: mpop calls pop $k$ times
- Assume any sequence $Q$ of operations push, pop, mpop
- E.g. Q=\{push,push,mpop(k),push,pop,push,mpop(k),...\}
- Assume costs $c($ push $)=1, c(p o p)=1, c(m p o p(k))=k$
- With $|\mathrm{Q}|=\mathrm{n}$ : What cost do we expect for a given Q ?
- Every op in Q costs 1 (push) or 1 (pop) or $k$ (mpop)
- In the worst case, $k$ can be $\sim n$ ( $n$ times push, then one mpop(n))
- Worst case of a single operation is O(n)
- Total worst-case cost: O(n²)

> Note: Costs only ~2*n

## Problem

- Clearly, the cost of Q is in $\mathrm{O}\left(\mathrm{n}^{2}\right)$, but this is not tight
- A simple thought shows: The cost of Q is in $\mathrm{O}(\mathrm{n})$
- Every element can be popped only once
- No matter if this happens through a pop or a mpop
- Pushing an element costs 1, popping it costs 1
- Q can at most push n elements and, hence, only pop $n$ elements
- Thus, the total cost is in $O(n)$
- It is maximally $2^{*}(n-1)$
- We want to derive such a result in a systematic manner (analyzing SOLs is not that easy)


## Example 2: Bit-Counter

- We want to generate bitstrings by iteratively adding 1
- Starting from 0
- Assume bitstrings of length k
- Roll-over counter if we exceed $2^{k}$-1
- Q is a sequence of „${ }^{\prime}+1^{"}$
- We count as cost of an operation the number of bits we have to flip
- Classical WC analysis
- A single operation can flip up to $k$ bits - "1111111" +1
- Worst case cost for Q: O(k*n)

| 00000000 |  |  |
| :--- | :---: | :---: |
| 00000001 | 1 | 1 |
| 00000010 | 2 | 3 |
| 00000011 | 1 | 4 |
| 00000100 | 3 | 7 |
| 00000101 | 1 | 8 |
| 00000110 | 2 | 10 |
| 00000111 | 1 | 11 |
| 00001000 | 4 | 15 |
| 00001001 | 1 | 16 |
| 00001010 | 2 | 18 |
| $\ldots$ |  |  |

## Problem

- Again, this complexity is overly pessimistic / not tight
- Cost actually is in O(n)
- The right-most bit is flipped in every operation: cost=n
- The second-rightmost bit is flipped every second time: $\mathrm{n} / 2$
- The third ...: n/4
- Together

$$
\sum_{i=0}^{k-1} \frac{n}{2^{i}}<n * \sum_{i=0}^{\infty} \frac{1}{2^{i}}=2 * n
$$

- Two Examples
- Two Analysis Methods
- Accounting Method
- Potential Method
- Dynamic Tables
- SOL - Analysis


## Accounting Analysis

- Idea: We create an account for Q
- Operations put / withdraw some amounts of "money"
- We choose these amounts such that the current state of the account is always (throughout Q) an upper bound of the actual cost incurred by Q
- Let $c_{i}$ be the true cost of operation $i, d_{i}$ its effect on the account
- We require

$$
\forall 1 \leq k \leq n: \sum_{i=1}^{k} c_{i} \leq \sum_{i=1}^{k} d_{i}
$$

- Especially, the account must never become negative
- " $\leq "$ gives us more freedom in analysis than "="
- It follows: An upper bound for the account (d) after Q is also an upper bound for the true cost (c) of Q


## Application to mpop

- Assume $\mathrm{d}_{\text {push }}=2, \mathrm{~d}_{\text {pop }}=0, \mathrm{~d}_{\text {mpop }}=0$
- Upper bounds?
- Clearly, $d_{\text {push }}$ is an upper bound on $c_{\text {push }}$ (which is 1 )
- But neither $d_{\text {pop }}$ nor $d_{\text {mpop }}$ are upper bounds for $c_{\text {pop }} / c_{\text {mpop }}$
- Let's try: $\mathrm{d}_{\text {push }}=2, \mathrm{~d}_{\text {pop }}=1, \mathrm{~d}_{\text {mpop }}=\mathrm{n}$
- Now all individual d's are upper bounds for their c's
- But this doesn't help (worst-case analysis)

$$
\sum_{i=1}^{n} c_{i} \leq \sum_{i=1}^{n} d_{i} \leq n^{*} n \in O\left(n^{2}\right)
$$

- But: We only have to show that the sum of d's for any prefix of $Q$ is higher than the sum of c's


## Application to mpop

- Assume $d_{\text {push }}=2, d_{\text {pop }}=0, d_{\text {mpop }}=0$
- Summing these up yields an upper bound on the real cost
- Idea: Whenever we push an element, we pay 1 for the push and 1 for the operation that will (at same later time) pop exactly this element
- It doesn't matter whether this will be through a pop or a mpop
- Note: For every pop, there must have been a corresponding push before
- Thus, when it comes to a pop or mpop, there is always enough money on the account
- Deposited by previous push's
- "enough": Enough such that the sum remains an upper bound
- This proves:

$$
\sum_{i=1}^{n} c_{i} \leq \sum_{i=1}^{n} d_{i} \leq 2 * n \in O(n)
$$

## Choose d's carefully

- Assume $\mathrm{d}_{\text {push }}=1, \mathrm{~d}_{\text {pop }}=1, \mathrm{~d}_{\text {mpop }}=1$
- Assume Q=\{push,push,push,mpop(3)\}
- $\Sigma \mathrm{c}=6>\Sigma \mathrm{d}=4$
- Assume $\mathrm{d}_{\text {push }}=1, \mathrm{~d}_{\text {pop }}=0, \mathrm{~d}_{\text {mpop }}=0$
- Assume Q=\{push,push,mpop(2)\}
- $\Sigma \mathrm{c}=4>\sum \mathrm{d}=2$
- Assume $d_{\text {push }}=3, d_{\text {pop }}=0, d_{\text {mpop }}=0$
- Fine as well, but not as tight (but also leads to O(n))


## Application to Bit-Counter

- Look at the sequence $\mathrm{Q}^{\prime}$ of flips generated by a sequence Q
- Every +1 creates a sequence of [0,k] flip-to-0 and [0,1] flip-to-1
- There is no „flip to $1^{"}$ if we roll-over
- Since only flips cost, the cost of Q' is the same as the cost of Q
- Let's try $\mathrm{d}_{\text {fip-to }-1}=2$ and $\mathrm{d}_{\text {fipp-to- } 0}=0$
- Clearly, $\mathrm{d}_{\text {filp-to-1 }}$ is an upper bound to $\mathrm{c}_{\text {flip-to-1 }}$
- Note: We start with only 0 and can flip-to-0 any 1 only once
- Before we flip-to-1 again, again enabling one flip-to-0 etc.
- Idea: When we flip-to-1, we pay 1 for flipping and 1 for the back-flip-to-0 that might happen at some later time in Q'
- There can be only one flip-to-0 per flip-to-1
- Thus, the account is always an upper bound on the actual cost


## Application to Bit-Counter -2-

- We know that the account is always an upper bound on the actual cost for any prefix of Q
- Every step of Q creates a sequence of flip-to-1 (at most one) and flip-to-0 in Q'
- This sequence costs at most 2
- There can be only on flip-to-1, and all fli-to-0 are free
- Every step in Q costs at most 2
- Thus, Q is bound by $\mathrm{O}(\mathrm{n})$
- qed.
- Two Examples
- Two Analysis Methods
- Accounting Method
- Potential Method
- Dynamic Tables
- SOL - Analysis


## Potential Method: Idea

- In the accounting method, we assign a cost to every operation and compare aggregated accounting costs of ops with aggregated real costs of ops
- In the potential method, we assign a potential $\Phi(\mathrm{D})$ to the data structure D manipulated by Q
- As ops from Q that change D, also change D's potential
- The trick is to design $\Phi$ such that we can (again) use it to derive an upper bound on the real cost of Q
- "Accounting" and "potential" methods are quite similar use whatever is easier to apply for a given problem


## Potential Function

- Let $D_{0}, D_{1}, \ldots D_{n}$ be the states of $D$ when applying $Q$
- We define the amortized cost $d_{i}$ of the i'th operation as $d_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)$
- We derive the amortized cost of Q as

$$
\sum_{i=1}^{n} d_{i}=\sum_{i=1}^{n}\left(c_{i}+\phi\left(D_{i}\right)-\phi\left(D_{i-1}\right)\right)=\sum_{i=1}^{n} c_{i}+\phi\left(D_{n}\right)-\phi\left(D_{0}\right)
$$

- Rough idea: If we find a $\Phi$ such that (a) we can obtain formulas for the amortized costs for all individual $\mathrm{d}_{\mathrm{i}}$ and (b) $\Phi\left(D_{n}\right) \geq \Phi\left(D_{0}\right)$, we have an upper bound for the real costs
- Because then:

$$
\sum_{i=1}^{n} d_{i}=\sum_{i=1}^{n} c_{i}+\phi\left(D_{n}\right)-\phi\left(D_{0}\right) \geq \sum_{i=1}^{n} c_{i}
$$

## Details: Always Pay in Advance

- Operations raise or lower the potential (~future cost) of $D$
- We need to find a function $\Phi$ such that
- Req. 1: $\Phi\left(D_{i}\right)$ depends on a property of $D_{i}$
- Req. 2: $\Phi\left(D_{n}\right) \geq \Phi\left(D_{0}\right)$ [and we will always have $\Phi\left(D_{0}\right)=0$ ]
- Req. 3: We can compute $d_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)$
- As within a sequence we do not know its future, we also have to require that $\Phi\left(D_{i}\right)$ never is negative
- Otherwise, the amortized cost of the prefix Q[1-i] would not be an upper bound of the real costs at step i
- Idea: Always pay in advance


## Example: mpop

- We use the number of objects on the stack as its potential
- Then
- Req. 1: $\Phi\left(D_{i}\right)$ depends on a property of $D_{i}$
- Req. 2: $\Phi\left(D_{n}\right) \geq \Phi\left(D_{0}\right)$ and $\Phi\left(D_{0}\right)=0$
- Req. 3: Compute $d_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)$ for all ops:
- If op is push: $\mathrm{d}_{\mathrm{i}}=\mathrm{c}_{\mathrm{i}}+(\mathrm{x}-(\mathrm{x}-1))=1+1=2$
- If op is pop: $d_{i}=c_{i}+(x-(x+1))=1-1=0$
- If op is $\operatorname{mpop}(k): d_{i}=c_{i}+(x-(x+k))=k-k=0$
- Thus, $2^{*} n \geq \Sigma d_{i} \geq \sum c_{i}$ and $Q$ is in $O(n)$


## Example: Bit-Counter

- We use the number of „1" in the bitstring as its potential
- Then
- Req. 1: $\Phi\left(D_{i}\right)$ depends on a property of $D_{i}$
- Req. 2: $\Phi\left(D_{n}\right) \geq \Phi\left(D_{0}\right)$ and $\Phi\left(D_{0}\right)=0$
- Req. 3: We compute $d_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)$ for all ops
- Let the i'th operation incur $t_{i}$ flip-to-0 and 0 or 1 flip-to-1
- Thus, $\mathrm{c}_{\mathrm{i}} \leq \mathrm{t}_{\mathrm{i}}+1$
- If $\Phi\left(D_{i}\right)=0$, then operation $i$ has flipped all positions to 0 ; this implies that previously they were all 1 , which means that $\Phi\left(D_{i-1}\right)=k$
- If $\Phi\left(D_{i}\right)>0$, then $\Phi\left(D_{i}\right)=\Phi\left(D_{i-1}\right)-t_{i}+1$
- In both cases, we have $\Phi\left(D_{i}\right) \leq \Phi\left(D_{i-1}\right)-t_{i}+1$
- Thus, $\mathrm{d}_{\mathrm{i}}=\mathrm{c}_{\mathrm{i}}+\Phi\left(\mathrm{D}_{\mathrm{i}}\right)-\Phi\left(\mathrm{D}_{\mathrm{i}-1}\right) \leq\left(\mathrm{t}_{\mathrm{i}}+1\right)+\left(\Phi\left(\mathrm{D}_{\mathrm{i}-1}\right) \mathrm{t}_{\mathrm{i}}+1\right)-\Phi\left(\mathrm{D}_{\mathrm{i}-1}\right) \leq 2$
- Thus, $2 * n \geq \Sigma \mathrm{d}_{\mathrm{i}} \geq \Sigma \mathrm{c}_{\mathrm{i}}$ and Q is in $\mathrm{O}(\mathrm{n})$
- Two Examples
- Two Analysis Methods
- Dynamic Tables
- SOL are complicated ... we still try to get familiar with the analysis method using simpler problems ...
- SOL - Analysis


## Dynamic Tables

- We use amortized analysis for something more useful: Complexity of operations on a dynamic table
- Assume an array T and a sequence Q of insert/delete ops
- Dynamic Tables: Keep the array small, yet avoid overflows
- Start with a table T of size 1
- When inserting and T is full, we double |T|; upon deleting and T is only half-full, we reduce |T| by $50 \%$
- "Doubling", "reducing" means: Copying data to a new array
- Copying an element of an array costs 1
- Thus, any operation (ins or del) costs either 1 or i


## Example

```
\(\square\)
insert(1) 1\
insert(2) [1/2)
insert(3) (1)23% 
```



```
insert(5); insert(6); insert(7) [1/ \
```



```
delete(4) [1 [2)
```


## With Potential Method

$$
\begin{aligned}
& \text { 1: } \Phi\left(D_{i}\right) \text { depends on a property of } D_{i} \\
& \text { 2: } \Phi\left(D_{n}\right) \geq \Phi\left(D_{0}\right) \\
& \text { 3: } d_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)
\end{aligned}
$$

- Let num(T) be the current number of elements in $T$
- We use potential $\Phi(T)=2 * n u m(T)-|T|$
- Intuitively a "potential"
- Immediately before an expansion, $\operatorname{num}(T)=|T|$ and $\Phi(T)=|T|$, so there is much potential in T (we saved for the expansion to come)
- Immediately after an expansion, num $(\mathrm{T})=|\mathrm{T}| / 2$ and $\Phi(\mathrm{T})=0$; all potential has been used, we need to save again for the next expansion
- Formally
- Requirement 1: Of course
- Requirement 2: As T is always at least half-full, $\Phi(\mathrm{T})$ is always $\geq 0$; we start with $|T|=0$, and thus $\Phi\left(T_{n}\right)-\Phi\left(T_{0}\right) \geq 0$


## Continuation

$$
\begin{aligned}
& \text { 1: } \Phi\left(D_{i}\right) \text { depends on a property of } D_{i} \\
& \text { 2: } \Phi\left(D_{n}\right) \geq \Phi\left(D_{0}\right) \\
& \text { 3: } d_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right) f
\end{aligned}
$$

- Req. 3: Let's look at $d_{i}=c_{i}+\Phi\left(T_{i}\right)-\Phi\left(T_{i-1}\right)$ for insertions
- Without expansion

$$
\begin{aligned}
\mathrm{d}_{\mathrm{i}} \quad & =1+\left(2^{*} \operatorname{num}\left(\mathrm{~T}_{\mathrm{i}}\right)-\left|\mathrm{T}_{i}\right|\right)-\left(2^{*} \operatorname{num}\left(\mathrm{~T}_{\mathrm{i}-1}\right)-\left|\mathrm{T}_{\mathrm{i}-1}\right|\right) \\
& =1+2^{*} \operatorname{num}\left(\mathrm{~T}_{\mathrm{i}}\right)-2^{*} \operatorname{num}\left(\mathrm{~T}_{\mathrm{i}-1}\right)-\left|\mathrm{T}_{\mathrm{i}}\right|+\left|\mathrm{T}_{\mathrm{i}-1}\right| \\
& =1+2+0 \\
& =3
\end{aligned}
$$

- With expansion

$$
\begin{array}{rlc}
d_{i} & =\operatorname{num}\left(T_{i}\right)+\quad\left(2^{*} \operatorname{num}\left(T_{i}\right)-\left|T_{i}\right|\right) \quad-\quad\left(2^{*} \operatorname{num}\left(T_{i-1}\right)-\left|T_{i-1}\right|\right) \\
& =\operatorname{num}\left(T_{i}\right)+\quad 2^{*} \operatorname{num}\left(T_{i}\right)-\left|T_{i}\right| \quad-\quad 2^{*} \operatorname{num}\left(T_{i-1}\right)+\left|T_{i-1}\right| \\
& =\operatorname{num}\left(T_{i}\right)+2^{*} \operatorname{num}\left(T_{i}\right)-2^{*}\left(\operatorname{num}\left(T_{i}\right)-1\right)-2^{*}\left(\operatorname{num}\left(T_{i}\right)-1\right)+\operatorname{num}\left(T_{i}\right)-1 \\
& =3^{*} \operatorname{num}\left(T_{i}\right)-2^{*} \operatorname{num}\left(T_{i}\right)+2-2^{*} \operatorname{num}\left(T_{i}\right)+2+\operatorname{num}\left(T_{i}\right)-1 \\
& =3
\end{array}
$$

- Thus, $3^{*} n \geq \Sigma \mathrm{d}_{\mathrm{i}} \geq \Sigma \mathrm{c}_{\mathrm{i}}$ and Q is in $\mathrm{O}(\mathrm{n})$ (for only insertions)


## Intuition

- Think accounting method
- For insert', we deposit 3 because
- 1 for the insertion (the real cost)
- 1 for the time when we need to copy this new element at the next expansion
- These 1's fill the account with $\left|T_{i}\right| / 2$ before the next expansion
- 1 for one of the $\left|T_{i}\right| / 2$ elements already in A after the last expansion

| 1 | 2 | 3 | 4 | 5 |
| :--- | :--- | :--- | :--- | :--- |





- These fill the account with $\left|\mathrm{T}_{\mathrm{i}}\right| / 2$ before the next expansion
- Thus, we have enough credit at the next expansion


## Problem: Deletions

- Our strategy for deletions so far is not very clever
- Assume a table with num(T)=|T|
- Assume a sequence $Q=\{I, D, I, D, I, D, I \ldots\}$
- This sequence will perform $|T|+|T| / 2+|T|+|T| / 2+\ldots$ real ops
- As $|T|$ is $O(n), Q$ is in $O\left(n^{2}\right)$ and not in $O(n)$
- Simple trick: Do only contract when num $(T)=|T| / 4$
- Leads to amortized cost of $O(n)$ for any sequence of operations
- We omit the proof (see [Cor03])
- Two Examples
- Two Analysis Methods
- Dynamic Tables
- SOL - Analysis
- Goal and idea
- Preliminaries
- A short proof


## Re-Organization Strategies

- Recall self-organizing lists (SOL)
- As usual: Accessing the i'th element costs i
- When searching an element, we change the list L
- Three popular strategies
- MF, move-to-front:
- T, transpose:

- FC, frequency count:



## Notation

- Assume we have a strategy A and a workload S on list L
- After accessing element i, A may move i by swapping
- Swap with predecessor (to-front) or successor (to-back)
- Let $F_{A}(I)$ be the number of front-swaps and $X_{A}(I)$ the number of back-swaps of step I when using strategy $A$
- This means: $\mathrm{F}_{\mathrm{MF}} \mathrm{X}_{\mathrm{MF}}$ for strategy MF, $\mathrm{F}_{\mathrm{T}} / X_{\mathrm{T}} \ldots \mathrm{F}_{\mathrm{FC}} / X_{\mathrm{FC}}$
- We never back-swap: $\forall I: X_{\text {MF }}(I)=X_{T}(I)=X_{F C}(I)=0$
- Let $\mathrm{C}_{\mathrm{A}}(\mathrm{S})$ be the total access cost of A incurred by S
- Again: $\mathrm{C}_{\mathrm{MF}}$ for strategy MF, $\mathrm{C}_{\mathrm{T}}$ for $\mathrm{T}, \mathrm{C}_{\mathrm{FC}}$ for FC
- With conventional worst-case analysis, we can only derive that $C_{A}(S)$ is in $O\left(|S|^{*}|L|\right)$ - for any $A$


## Theorem

- Theorem (Amortized costs)

Let A be any self-organizing strategy for a SOL L, MF be the move-to-front strategy, and $S$ be a sequence of accesses to $L$. Then

$$
G_{\mathrm{MF}}(S) \leq 2^{*} C_{\mathrm{A}}(S)+X_{\mathrm{A}}(S)-F_{\mathrm{A}}(S)-/ S /
$$

- What does this mean?
- We don't learn more about the absolute complexity of SOLs
- But we learn that MF is quite good
- Any strategy following the same constraints (only series of swaps) will at best be roughly twice as good as MF
- Assuming $\mathrm{C}_{\mathrm{A}}(\mathrm{S}) \gg|\mathrm{S}|$ and for $|\mathrm{S}| \rightarrow \infty$ : $\mathrm{X}(\mathrm{S}) \sim \mathrm{F}(\mathrm{S})$ for any strategy
- Despite its simplicity, MF is a fairly safe bet for all workloads


## Idea of the Proof

- We will compare access costs in $L$ between MF and any A
- Think of both strategies (MF, A) running S on two copies of the same initial list L
- After each step, A and MF perform different swaps, so all list states except the first very likely are different
- We will compare list states by looking at the number of inversions ("Fehlstellungen")
- Actually, we only analyze how the number of inversions changes
- We will show that the number of inversions defines a potential of a pair of lists that helps to derive an upper bound on the differences in real costs


## Content of this Lecture

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- A short proof


## Inversions

- Let $L$ and L ' be permutation of the set $\{1,2, \ldots, n\}$
- Definition
- A pair (i,j) is called an inversion of $L$ and $L^{\prime}$ iff $i$ and $j$ are in different order in $L$ than in $L$ ' (for $1 \leq i, j \leq n$ and $i \neq j$ )
- The number of inversions between $L$ and $L^{\prime}$ is denoted by inv( $L, L$ ')
- Remarks
- Different order: Once i before j, once i after j
- Obviously, inv(L, L') $=\operatorname{inv}\left(L^{\prime}, L\right)$
- Example: inv( $\{4,3,1,5,7,2,6\},\{3,6,2,5,1,4,7\}$ ) $=12$
- Without loss of generality, we assume that $\mathrm{L}=\{1, . ., \mathrm{n}\}$
- Because we only look at changes in number of inversions and not at the actual set of inversions


## Sequences of Changes

- Assume we applied $I-1$ steps of $S$ on $L$, creating $L_{\text {MF }}$ using MF and $L_{A}$ using $A$
- Let us consider the next step I, creating $\mathrm{L}_{\mathrm{MF}}{ }^{\prime}$ and $\mathrm{L}_{\mathrm{A}}{ }^{\prime}$



## Inversion Changes

- How does I change the number of inv's between $L_{\text {mF }} / L_{A}$ ?
- Can we compute $\operatorname{inv}\left(L_{M F}{ }^{\prime}, L_{A}{ }^{\prime}\right)$ from $\operatorname{inv}\left(L_{M F}, L_{A}\right)$ ?
- Assume step I accesses element i from $L_{A}$
- We may assume it is at position i
- Let this element $i$ be at position $k$ in $L_{\text {mF }}$
- Access in $L_{A}$ costs $i$, access in $L_{\text {MF }}$ costs $k$
- After step $\mathrm{I}, \mathrm{A}$ performs an unknown number of swaps; MF performs exactly $k$ - 1 front-swaps



## Counting Inversion Changes 1



- Let $X_{1}$ be the set of values that are before position k in $L_{M F}$ and after position i in $L_{A}$

- Le $Y_{1}$ be the values before position $k$ in $L_{M F}$ and before $i$ in $L_{A}$
- Clearly, $\left|X_{\|}\right|+\left|Y_{\mid}\right|=k-1$
- All pairs ( $\mathrm{i}, \mathrm{c}$ ) with $\mathrm{C} \in \mathrm{X}_{\mathrm{I}}$ are inversions between $\mathrm{L}_{\mathrm{A}}$ and $\mathrm{L}_{\mathrm{MF}}$
- There may be more; but only those with i are affected in this step
- After step I, MF moves element $i$ to the front
- Assume first that A does simply nothing
- All inversions ( $\mathrm{i}, \mathrm{c}$ ) with $\mathrm{c} \in \mathrm{X}_{1}$ disappear (there are $\left|X_{\mid}\right|$many)
- But $\left|Y_{\mid}\right|=k-1-\left|X_{\mid}\right|$new inversions appear
- Thus: $\operatorname{inv}\left(L_{M F}{ }^{\prime}, L_{A}{ }^{\prime}\right)=\operatorname{inv}\left(L_{M F}, L_{A}\right)-\left|X_{l}\right|+k-1-\left|X_{l}\right|$
- But A does something


## Counting Inversion Changes 2

- In step I, let A perform $\mathrm{F}_{\mathrm{A}}(\mathrm{I})$ front-swaps and $X_{A}(I)$
 back-swaps
- Every front-swap (swapping i before any j) in $L_{A}$ decreases $\operatorname{inv}\left(L_{M F}, L_{A}{ }^{\prime}\right)$ by 1
- Before step I , j must be before i in $\mathrm{L}_{A}$ (it is a front-swap), but after i in $\mathrm{L}_{\mathrm{MF}}{ }^{\prime}$ (because i now is the first element in $\mathrm{L}_{\mathrm{MF}}{ }^{\prime}$ )
- After step $\mathrm{I}, \mathrm{i}$ is before j in both $\mathrm{L}_{A^{\prime}}$ and $\mathrm{L}_{\mathrm{MF}}{ }^{\prime}$ - inversion removed
- Equally, every back-swap increases inv $\left(\mathrm{L}_{M F}{ }^{\prime}, \mathrm{L}_{\mathrm{A}}{ }^{\prime}\right)$ by 1
- Together: After step I, we have

$$
\operatorname{inv}\left(L_{M F}^{\prime}, L_{A}^{\prime}\right)=\underbrace{\operatorname{inv}\left(L_{M F}, L_{A}\right)}_{\text {Before step } 1}-\underbrace{\left|X_{y}\right|+\left|-1-\left|X_{y}\right|\right.}_{\text {through MF }}-\underbrace{F_{A}(\|)+X_{A}(\|)}_{\text {through } A}
$$

## Amortized Costs

Was $c_{1} \ldots$ was $d_{1} . .$. we switch to Cor notation

- Let $\mathrm{t}_{\mathrm{MF}}(\mathrm{I})$ be the real cost of strategy MF for step I
- We use the number of inversions as potential function $\Phi\left(L_{A}, L_{M F}\right)=i n v\left(L_{a}, L_{M F}\right)$ on the pair $L_{A}, L_{M F}$
- Definition
- The amortized costs of step I, called $a_{1}$, are

$$
a_{l}=t_{M F}(I)+\operatorname{inv}\left(L_{A}(I), L_{M F}(I)\right)-\operatorname{inv}\left(L_{A}(l-1), L_{M F}(l-1)\right)
$$

- Accordingly, the amortized costs of sequence $S, \mid S /=m$, are

$$
\Sigma a_{l}=\Sigma t_{M F}(I)+\operatorname{inv}\left(L_{A}(m), L_{M F}(m)\right)-\operatorname{inv}\left(L_{A}(0), L_{M F}(0)\right)
$$

- This is a proper potential function
- 1: $\Phi$ depends on a property of the pair $L_{A}, L_{M F}$
- 2: inv() can never be negative, so $\forall \mathrm{l}$ : $\Phi\left(\mathrm{L}_{\mathrm{A}}(\mathrm{I}), \mathrm{L}_{\text {MF }}(\mathrm{I})\right) \geq \Phi(\mathrm{L}, \mathrm{L})=0$
- Let's look at how operations change the potential


## Content of this Lecture

- Two Examples
- Two Analysis Methods
- Dynamic Tables
- SOL - Analysis
- Goal and idea
- Preliminaries
- A short proof (after much preparatory work)


## Putting it Together

- We know for every step I from workload S accessing i : $\operatorname{inv}\left(L_{M F}{ }^{\prime}, L_{A}{ }^{\prime}\right)=\operatorname{inv}\left(L_{M F}, L_{A}\right)-\left|X_{\mid}\right|+k-1-\left|X_{I}\right|-F_{A}(I)+X_{A}(I)$ and thus
$\operatorname{inv}\left(L_{M F}{ }^{\prime}, L_{A}{ }^{\prime}\right)-\operatorname{inv}\left(L_{M F}, L_{A}\right)=-\left|X_{\mid}\right|+k-1-\left|X_{I}\right|-F_{A}(I)+X_{A}(I)$
- Since $t_{M F}(I)=k$, we get amortized costs of

$$
\begin{aligned}
a_{\mid} & =t_{M F}(I)+\operatorname{inv}\left(L_{A}^{\prime}, L_{M F}{ }^{\prime}\right)-\operatorname{inv}\left(L_{A}, L_{M F}\right) \\
& =k-\left|X_{\mid}\right|+k-1-\left|X_{\|}\right|-F_{A}(I)+X_{A}(I) \\
& =2\left(k-\left|X_{1}\right|\right)-1-F_{A}(I)+X_{A}(I)
\end{aligned}
$$

- Recall that $Y_{1}\left(\left|Y_{\mid}\right|=k-1-\left|X_{\mid}\right|\right)$are those elements before $i$ in both lists. This implies that $k-1-\left|X_{\mid}\right| \leq i-1$ or $k-\left|X_{\mid}\right| \leq i$
- There can be at most $i-1$ elements before position $i$ in $L_{A}$
- Therefore: $\mathrm{a}_{1} \leq 2 \mathrm{i}-1-\mathrm{F}_{\mathrm{A}}(\mathrm{I})+\mathrm{X}_{\mathrm{A}}(\mathrm{I})$


## Putting it Together

- This is the central trick!
- Because we only looked at inversions (and hence the sequence of values), we ran draw a connection between the value that is accessed and the number of inversions that are affected
- Recall that $Y_{1}\left(\left|Y_{\mid}\right|=k-1-\left|X_{\mid}\right|\right)$are those elento ivefore $i$ in both lists. This implies that $k-1-\left|X_{1}\right| \leq i-1$ of $k-\left|X_{\mid}\right| \leq i$
- There can be at most i-1 elements before position 1 inini
- Therefore: $\mathrm{a}_{\mathrm{I}} \leq 2 \mathrm{i}-1-\mathrm{F}_{\mathrm{A}}(\mathrm{I})+\mathrm{X}_{\mathrm{A}}(\mathrm{I})$


## Aggregating

- We also know the cost of accessing $i$ using $A$ : that's $i$
- Together: $\mathrm{a}_{1} \leq 2 \mathrm{C}_{\mathrm{A}}(\mathrm{I})$ - $1-\mathrm{F}_{\mathrm{A}}(\mathrm{I})+\mathrm{X}_{\mathrm{A}}(\mathrm{I})$
- Aggregating this inequality over all $\mathrm{a}_{\mathrm{I}}$ in S , we get

$$
\Sigma \mathrm{a}_{1} \leq 2 * \mathrm{C}_{\mathrm{A}}(\mathrm{~S})-|\mathrm{S}|-\mathrm{F}_{\mathrm{A}}(\mathrm{~S})+\mathrm{X}_{\mathrm{A}}(\mathrm{~S})
$$

- By definition, we also have

$$
\Sigma \mathrm{a}_{1}=\Sigma \mathrm{t}_{\mathrm{MF}}(\mathrm{I})+\operatorname{inv}\left(\mathrm{L}_{\mathrm{A}}{ }^{m}, \mathrm{~L}_{\mathrm{MF}}{ }^{m}\right)-\operatorname{inv}\left(\mathrm{L}_{\mathrm{A}}{ }^{0}, \mathrm{~L}_{\mathrm{MF}}{ }^{0}\right)
$$

- Since $\sum \mathrm{t}_{\mathrm{MF}}(\mathrm{I})=\mathrm{C}_{\mathrm{MF}}(\mathrm{S})$ and $\operatorname{inv}\left(\mathrm{L}_{\mathrm{A}}{ }^{0}, \mathrm{~L}_{M F}{ }^{0}\right)=0$, we get

$$
C_{M F}(S)+\operatorname{inv}\left(L_{A}{ }^{m}, L_{M F}{ }^{m}\right) \leq 2 * C_{A}(S)-|S|-F_{A}(S)+X_{A}(S)
$$

- It finally follows (inv() $\geq 0$ )

$$
C_{M F}(S) \leq 2 * C_{A}(S)-|S|-F_{A}(S)+X_{A}(S)
$$

## Summary

- Self-organization creates a type of problem we were not confronted with before
- Things change during program execution
- But not at random - we follow a strategy
- Analysis is none-trivial, but
- Helped to find a elegant and surprising conjecture
- Very interesting in itself: We showed relationships between measures we never counted (and could not count easily)
- But beware the assumptions (e.g., only single swaps)
- Original work: Sleator, D. D. and Tarjan, R. E. (1985). "Amortized efficiency of list update and paging rules." Communications of the ACM 28(2): 202-208.

