

VORLESUNG

Automatisierung industrieller
Workflows

Teil C: Die Sprache SLX

- Vertiefung der Basissprache -

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Position

- ④ **Teil A**
Aspekte von Modellierung und Simulation dynamischer Systeme
- ④ **Teil B**
Die Modellierungssprache UML
- ④ **Teil C**
Die ausführbare Modellierungssprache SLX
- ④ **Teil D**
Weitere Modellierungssprachen
- ④ **Teil E**
Modellierung von Stahlwerksprozessen

- ④ **C.1**
Einführung und Basissprache
- ④ **C.2**
Stochastische Prozesse in SLX
- ④ **C.3**
Vertiefung der SLX-Basissprache
- ④ **C.4**
GPSS-Elemente
- ④ **C.5**
DISCO-Elemente
- ④ **C.6**
Basissprache (Ergänzung)

Vertiefung der Basissprache - Inhalt

1. Beispiel: Autofähre (Überblick)
2. Erinnerung: Set-Operationen
3. Beispiel: Autofähre (Ablauf)
4. Unterbrechung von per Interrupt
5. Beispiel: Drucker mit zeitweiligem Ausfall
6. Prozessparallelität
7. Prioritäten
8. Klassenvererbung

Inhalt der
letzten
Vorlesung

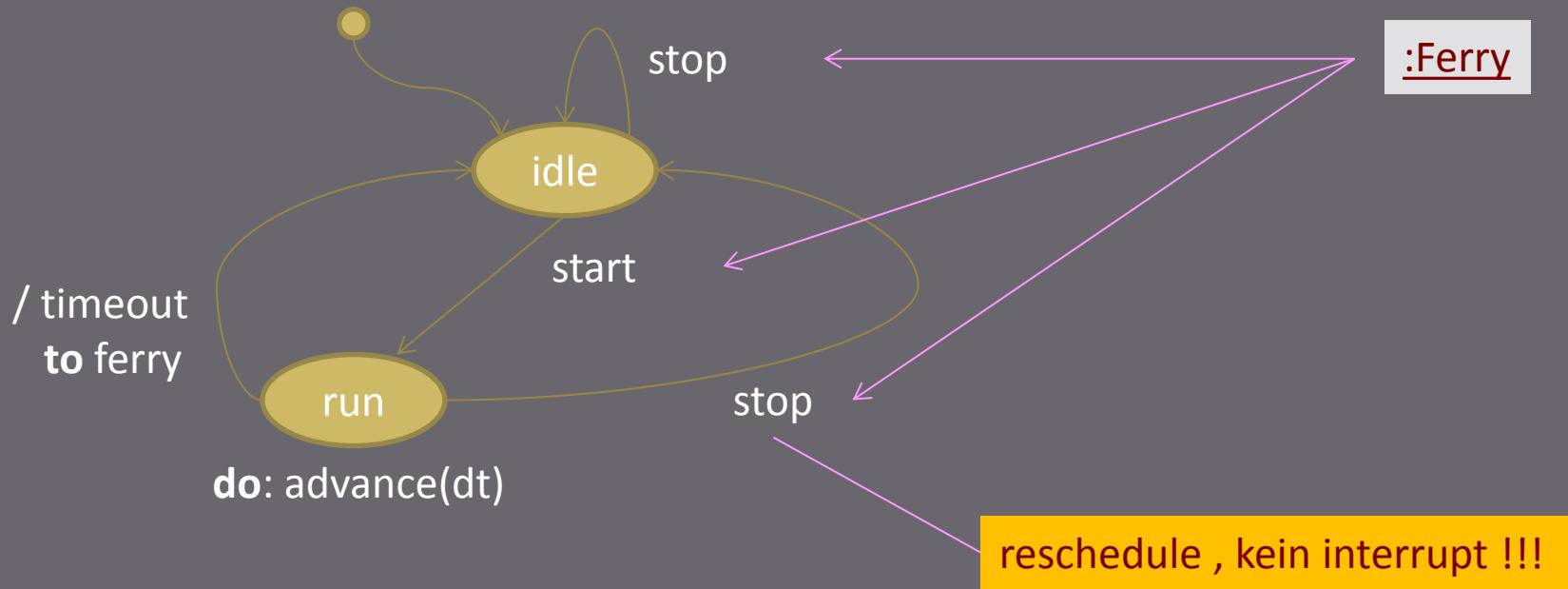
Einige Präzisierungen

Beispiel: Autofähre

- Wortmodell und informale Darstellung
- Erste Diskussion einer SLX-Implementation



Clock als UML-Zustandsautomat



letzte Vorlesung: Diskussion eines alternativen Interrupts

Idee

puck-Pointer->move_time

zu ändern,
scheitert (geschütztes Attribut im Gegensatz zu priority)

```
actions {  
    myPuck= ACTIVE;
```

```
    forever {  
        is_running= FALSE;  
        is_interrupted= FALSE;  
        wait;
```

Start

```
        has_timeout= FALSE;  
        is_running= TRUE;  
        #ifdef FERRY_DEBUG  
            print (time, name) "_____. .... _: Internal--- Start \n";  
        #endif  
        advance(alarmTime);
```

stop

```
        timeout  
        is_running= FALSE;  
        has_timeout= TRUE;  
        #ifdef FERRY_DEBUG  
            print options= red (time, name, myFerry->name) "_____. .... _: Internal ---TimeOut for: _ \n";  
        #endif  
        if (myFerry->myPuck->state == WAITING ) reactivate myFerry->myPuck;
```

```
        if ( is_interrupted) {  
            #ifdef FERRY_DEBUG  
                print options= bold (time, name, myFerry->name) "_____. .... _: is interrupted by _ \n";  
            #endif  
        }  
    } //forever
```

```
} //actions
```

```
method timer_stop () {  
    #ifdef FERRY_DEBUG  
        print (time, myFerry->name, name) "_____. ++++ _: stops _ \n";  
    #endif  
    if (is_running) {  
        #ifdef FERRY_DEBUG  
            print (time, myFerry->name, name) "_____. ++++ _ RESCHEDULES _ \n";  
        #endif  
        reschedule myPuck at time;  
        yield to myPuck;  
    }  
    is_interrupted= TRUE;
```

```
method timer_start () {  
    #ifdef FERRY_DEBUG  
        print (time, myFerry->name, name) "_____. ++++ _: restarts _ \n";  
    #endif  
    if (not is_running) {  
        reactivate myPuck;  
    }  
}
```

Offenes Problem: set (1)



set ist eigentlich ein generischer Listentyp

```
set(X) xs;  
set(X) ranked LIFO xsl;
```

```
class X {  
    int a;  
    int b;  
}
```

```
set(X) ranked  
(ascending a, descending b) s;
```

```
set(...) ranked FIFO <Name>  
set(...) ranked LIFO <Name>  
set(...) ranked (ascending a1, ...) <Name>  
set(...) ranked (descending d1, ...) <Name>
```

- einziger Mengentyp:
geordnete Menge von Objektzeigern
- Definition (homogenes Set):
set(<Klasse>) <Name>
- Definition (universelles Set):
set(*) <Name>
- Sortierung einstellbar:
 - **FIFO (Standard),**
 - **LIFO,**
 - aufsteigend/absteigend nach Attributen
(nur für homogene Sets)

Offenes Problem: set (2)

```
class X (int pa, pb) {
    int a;
    int b;
    initial {
        a= pa;
        b= pb;
    }
}

set(X) ranked
    (ascending a, descending b) container;

procedure main() {
    int i;
    int j;
    pointer(X) x, first_x;
    for ( i=1 ; i<=10 ; i++ ) {
        place new X(i, 0) into container;
    }
    for (x= each X in container) {
        j++;
        print (j, x->a, x->b) "_. Element ( a= _, b= _) \n";
    }
    first_x= last X in container;

    place new X(11,0) into container after first_x;
}
Semantic error: "container" is a ranked set; its ranking cannot be overridden
}
```

System – und Nutzer-Report

System Status at Time 488.0308

| <u>Random Stream</u> | <u>Sample Count</u> | <u>Initial Position</u> | <u>Current Position</u> | <u>Antithetic Variates</u> | <u>Chi-Square Uniformity</u> | |
|----------------------|---------------------|-------------------------|-------------------------|----------------------------|------------------------------|----------------------------------|
| Arrival 1 arrival | 80 | 400000 | 400080 | OFF | 0.19 | |
| Arrival 2 arrival | 75 | 600000 | 600075 | OFF | N/A | |
| trip | 42 | 200000 | 200042 | OFF | N/A | Versuchszahl ~ bislang zu gering |

| <u>Random Variable</u> | <u>#Observed</u> | <u>Mean or ~Value</u> | <u>Std Dev or ~Error</u> | <u>Sig. Digits</u> | <u>Minimum</u> | <u>Maximum</u> |
|------------------------|------------------|-----------------------|--------------------------|--------------------|----------------|----------------|
| trip_time | 12 | 4.138 | 2.488 | | 0.27 | 9.13 |

| <u>Lower</u> | <u>Upper</u> | <u>Frequency</u> | <u>Percent</u> | |
|--------------|--------------|------------------|----------------|-------|
| 0.0 | 0.5 | 1 | 8.333 | ***** |
| 1.0 | 1.5 | 2 | 16.667 | ***** |
| 3.5 | 4.0 | 3 | 25.000 | ***** |
| 4.0 | 4.5 | 1 | 8.333 | ***** |
| 5.0 | 5.5 | 3 | 25.000 | ***** |
| 6.0 | 6.5 | 1 | 8.333 | ***** |
| 9.0 | 9.5 | 1 | 8.333 | ***** |

Vehicles: 155

FERRY: Ferry 1

| | | |
|------------------|-------|------------|
| current vehicles | trips | transports |
| 0 | 12 | 136 |

Station: ISLAND current vehicles= 12

Station: MAINLAND current vehicles= 7

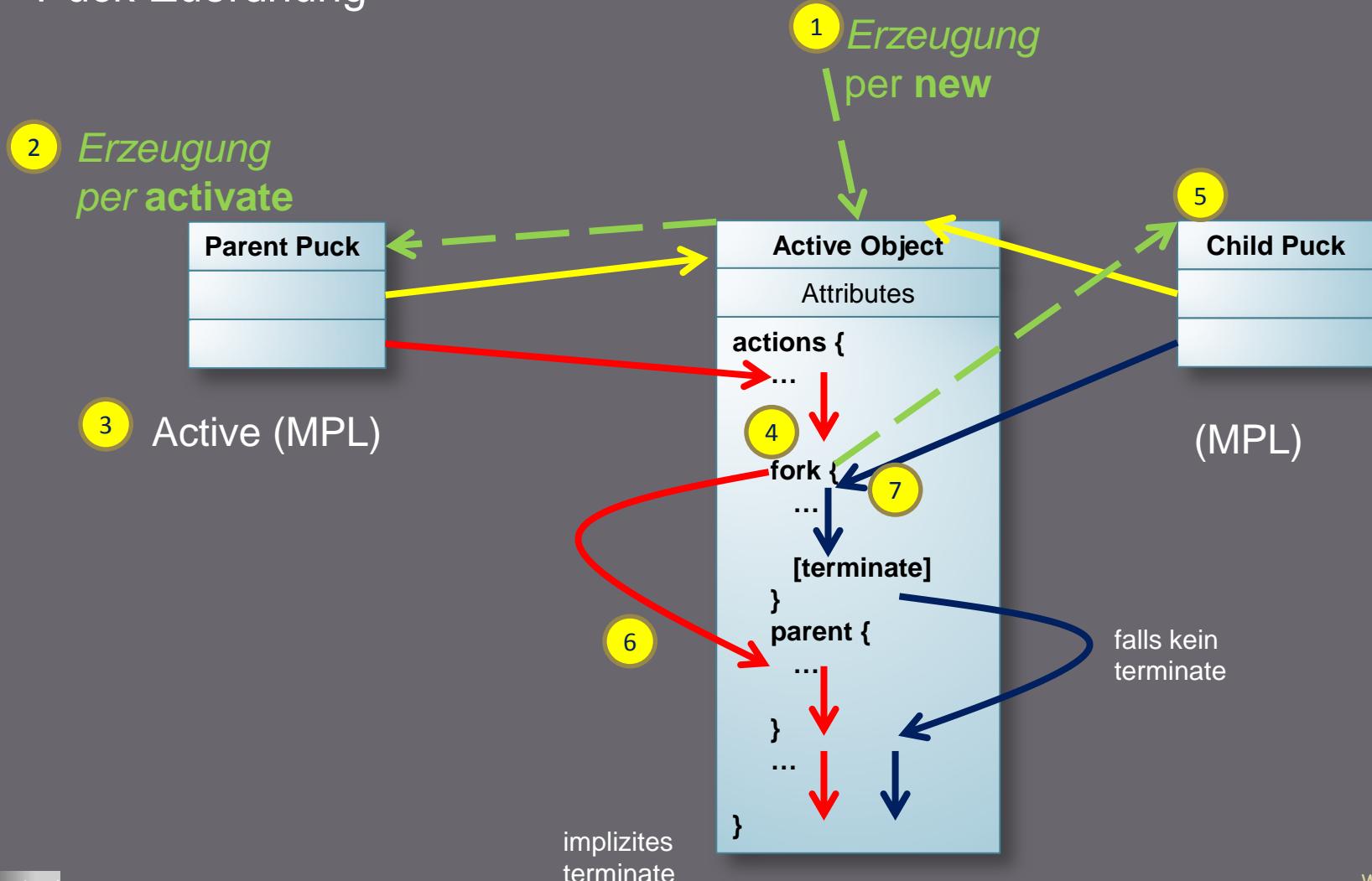
Execution complete

Vertiefung der Basissprache - Inhalt

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Interne Prozessparallelität

- Puck-Zuordnung



```

//*****  

// Module Basic EX0018  

//*****  

module basic {
    rn_stream arrivals, service ;
    int shutdown_time = 5*8*60, jobs_in, jobs_cancelled ;
    control int jobs_printed ;
    float total_queueing_time;
    pointer( cl_printer ) printer;
    set ( cl_printer_job ) waiting_line; // Queue for arriving jobs
}

```

```

class cl_printer_job ( in int in_job_num ) {
    int job_number;
    pointer ( puck ) my_puck; // Puck for Parent printer_job process
    initial {

```

```
        job_number = in_job_num;
```

```

    }
    actions {

```

```
        my_puck = ACTIVE; // Store the pointer to the parent puck
```

```
        place ME into waiting_line; // Place in Job Queue
```

```
        if ( not printer->printer_busy ) // Printer process sleeping?
```

```
            reactivate printer->my_puck;
```

```
fork { // local parallelism for Timeout
```

```
            pointer ( cl_printer_job ) temp_job;
```

```
            advance 1.5; // max. waiting time
```

```
            // Is my Job printing in the waiting line ?
```

```
            for ( temp_job = each cl_printer_job in waiting_line ) {
```

```
                if ( temp_job == ME ) {
```

```
                    remove ME from waiting_line ;
```

```
reactivate my_puck; // Child wakes the Parent
```

```
total_queueing_time += (time - temp_job->my_puck->mark_time); // Statistics
```

```
jobs_cancelled ++;
```

```
terminate;
```

```
}
```

```
}
```

```
} // fork
```

```
wait; // Sleep until wake up
```

```
my_puck = NULL ;
```

```
terminate ;
```

```
}
```

```
} // cl_printer_job
```

Parent Puck ~ PrinterJob

Child Puck ~ Wecker
zum Warte-Abbruch

Abbruch des Wartens
ohne Ausdruck

Frage: an welcher Stelle setzt
die Steuerung des Parent-Pucks
fortgesetzt ?

```

class cl_printer {
    control boolean printer_busy;
    pointer ( puck ) my_puck; // Puck for Printer Process
    pointer ( cl_printer_job ) owner; // Current Print Job

    actions {
        my_puck = ACTIVE; // Store the Pointer to the Puck
        forever {
            wait; // Wait for Print Jobs
            // While Contents of Job Queue != 0
            while ( (first cl_printer_job in waiting_line) != NULL ) {
                owner = first cl_printer_job in waiting_line; // Take First Job
                remove owner from waiting_line ;
                printer_busy = TRUE;
                total_queueing_time +=  

                    (time - owner->my_puck->mark_time); // Statistics
                advance rv_uniform ( service , 0.5, 15.0 ) ; // printing time
                printer_busy = FALSE;
                jobs_printed++;
                // Wake up the Sleeping Print Job Process
                reactivate owner->my_puck; //parent puck
                owner = NULL;
            } // while
        } // forever
    } // actions
}

procedure main() {
    printer = new cl_printer ;
    activate printer;
    while (time < shutdown_time) {
        jobs_in++;
        activate new cl_printer_job ( jobs_in ); // Create new jobs
        advance rv_uniform( arrivals , 10.0,20.0 ) ; // interarrivel time
    };
    wait until ( (jobs_in - jobs_cancelled) == jobs_printed);

    print ( jobs_in, jobs_cancelled, jobs_printed, total_queueing_time / jobs_printed*60 )
        "Incoming Jobs :_"
        ",Cancelled Jobs :_"
        "Printed Jobs :_"
        "Mean Queueing Time/Job : _._ seconds";
}
}

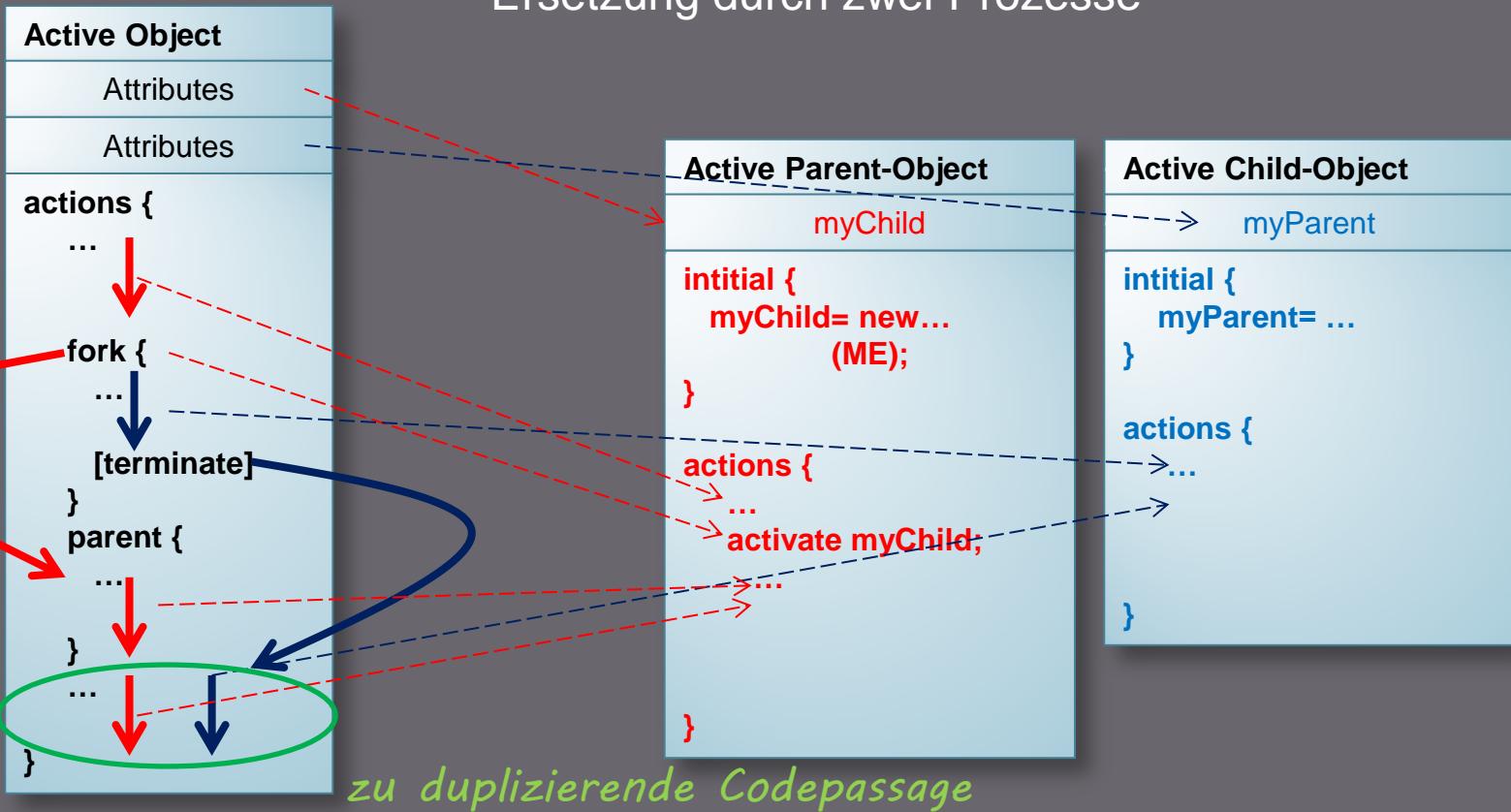
```

Beginn der Bedienung

Beendigung der Bedienung

Auflösung innerer Parallelität

Ersetzung durch zwei Prozesse



```

//*****
// Module Basic EX0018 modified
//*****

module basic {
    rn_stream arrivals, service ;
    int shutdown_time = 5*8*60,
        jobs_in,
        jobs_cancelled ;
    control int jobs_printed ;
    float total_queueing_time;
    pointer( cl_printer ) printer;
    set ( cl_printer_job ) waiting_line; // Queue for arriving jobs

    class cl_timer (in pointer (cl_printer_job) job) {           // urspruenglich Child
        pointer (cl_printer_job) owner;                         // Parent-Verweis
        initial {
            owner= job;
        }
        actions {
            advance 1.5; // max. waiting time
            // Is my job blocked in the waiting line ?
            if (waiting_line contains owner) {
                remove owner from waiting_line ;
                reactivate owner->my_puck; // wakes the blocked cl_printer_job
                total_queueing_time +=
                    (time -owner->my_puck->mark_time); // Statistics
                jobs_cancelled++;
            }
            owner= NULL;
            terminate ;
        }
    }
}

```

Abbruch des Wartens
auf Bedienung

durch Reaktivierung

```

class cl_printer_job ( in int in_job_num ) {
    int job_number;
    // Puck for Parent printer_job process
    pointer ( puck ) my_puck;
    pointer(cl_timer) my_timer;

    initial {
        job_number = in_job_num;
        my_timer= new cl_timer(ME);
    }

    actions {
        my_puck = ACTIVE; // Store the pointer to the puck
        place ME into waiting_line; // Place in Job Queue
        activate my_timer;
        if ( not printer->printer_busy ) // Printer process sleeping?
            reactivate printer->my_puck;
        wait; // Sleep until wake up
            // by timer without print or by printer after print
        my_puck = NULL ;
        terminate ;
    }
} // cl_printer_job

```

Abbruch des Wartens
oder Bedienungsende

```

class cl_printer {
    control boolean printer_busy;
    pointer ( puck ) my_puck; // Puck for Printer Process
    pointer ( cl_printer_job ) owner; // Current Print Job

    actions {
        my_puck = ACTIVE; // Store the Pointer to the Puck
        forever {
            wait; // Wait for Print Jobs
            // While Contents of Job Queue != 0
            while ( (first cl_printer_job in waiting_line) != NULL ) {
                owner = first cl_printer_job in waiting_line; // Take First Job
                remove owner from waiting_line ;
                printer_busy = TRUE;
                total_queueing_time +=  

                    (time - owner->my_puck->mark_time); // Statistics
                advance rv_uniform ( service , 0.5, 15.0 ) ; // printing time
                printer_busy = FALSE;
                jobs_printed++;
                // Wake up the Sleeping Print Job Process
                reactivate owner->my_puck;
                owner = NULL;
            } // while
        } // forever
    } // actions
}

```

Beendigung der Bedienung

```

procedure main() {
    printer = new cl_printer ;
    activate printer;
    while (time < shutdown_time) {
        jobs_in++;
        activate new cl_printer_job ( jobs_in ); // Create new jobs
        advance rv_uniform( arrivals , 10.0,20.0 ); // interarrival time
    };
    wait until ( (jobs_in - jobs_cancelled) == jobs_printed);

    print ( jobs_in,
            jobs_cancelled,
            jobs_printed ,
            total_queueing_time / jobs_printed*60 )

    "Incoming Jobs :_"
    „Cancelled Jobs :_”
    "Printed Jobs : _"
    "Mean Queueing Time/Job : __.____ seconds"
    ;
}
}

```

Ausgabe UNI [10, 20]

- Incoming Jobs : 163
- Cancelled Jobs : 6
- Printed Jobs : 157

Ausgabe UNI [5, 20]

- Incoming Jobs : 194
- Cancelled Jobs : 35
- Printed Jobs : 159

Ausgabe EXPO [5]

- Incoming Jobs : 470
- Cancelled Jobs : 271
- Printed Jobs : 199

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Prioritäten

Änderung der Priorität

- direkte Veränderung des Attributwertes
ACTIVE->priority = prio_value
- Aktivierung eines Prozesses
activate ptr_class_ident priority prio_value
- Reaktivierung eines Prozesses
reactivate ptr_class_ident priority prio_value
- Generierung von lokal parallelen Prozessen
fork priority prio_value

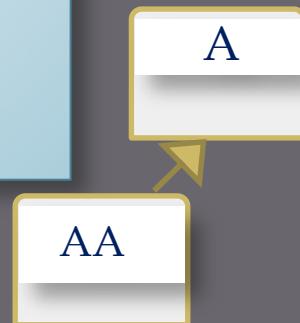
Vertiefung der Basissprache - Inhalt

1. Beispiel: Autofähre (Überblick)
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Vererbungsersatz

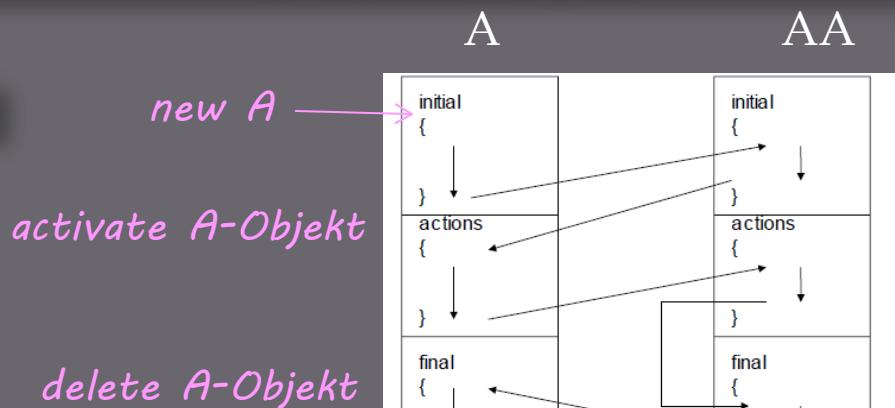
- Version 1.x Vererbungsersatz für Klassen

```
class A {  
    A1-attributes...  
    A1-Methoden...  
    A1-Properties...  
};  
  
augment A {  
    A2-attributes...  
    A2-Methoden...  
    A2-Properties...  
};
```



*A wird durch neues A (AA) ersetzt
(AA übernimmt altes A und fügt Attribute hinzu)*

```
set (A) liste_von_As; // Polymorphie,  
// d.h. Liste enthält AA-Objekte  
// aber keine A-Objekte
```



*korrekte Anwendung liegt
in der Hand des Nutzers*

Aktionsreihenfolge für Objekte
von Augment-Klassen

Vererbung

- ab Version 2.x Einfachvererbung für Klassen

```
class A {  
    A-attributes...  
};  
  
class B subclass (A) {  
    B-attributes...  
};  
  
class C subclass (B)  
    C-attributes...  
};  
....
```

```
set (A) liste_von_As; // Polymorphie,  
// d.h. Liste kann auch B-Objekte  
// enthalten
```

Liste_von_As kann keine E-Objekte enthalten

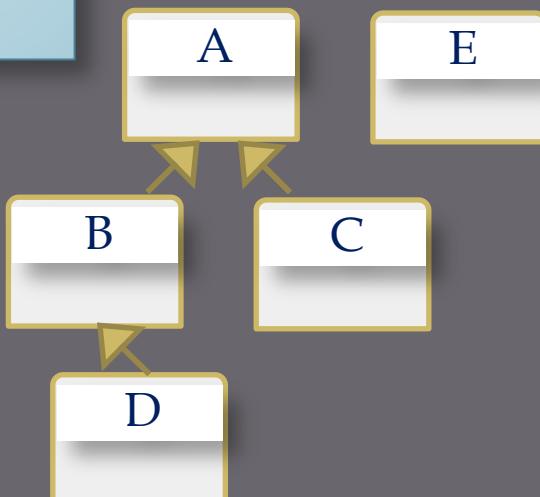
SLX2 erlaubt dynamischen Cast

```
ptr_B= ptr_A; //mit dynamischen Typtest  
//evtl. Laufzeitfehler
```

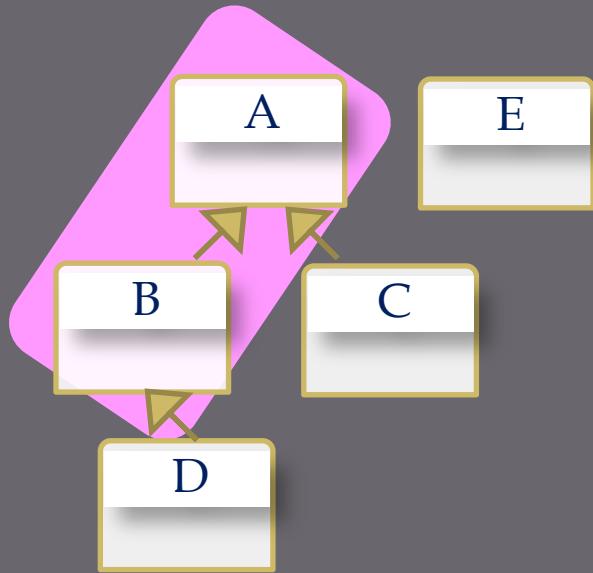
Basis- und abgeleitete Klasse können keine Attribute, Prozeduren oder Methoden gleichen Namens besitzen

Es sei denn, es handelt sich um redefinierbare Attribute, Prozeduren, Methoden

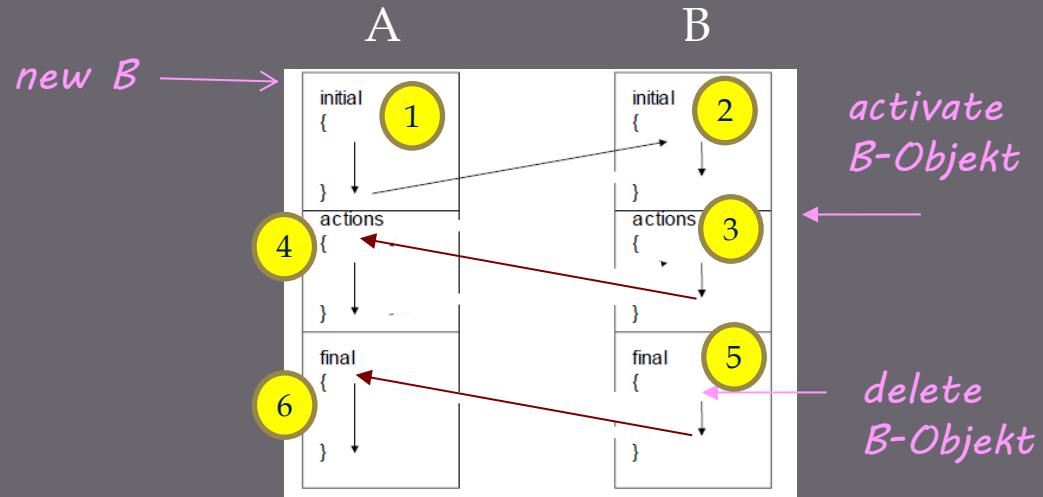
Benutzung der Version 2.0 muss explizit eingeschaltet werden:
`#define SLX2 ON`



Vererbung

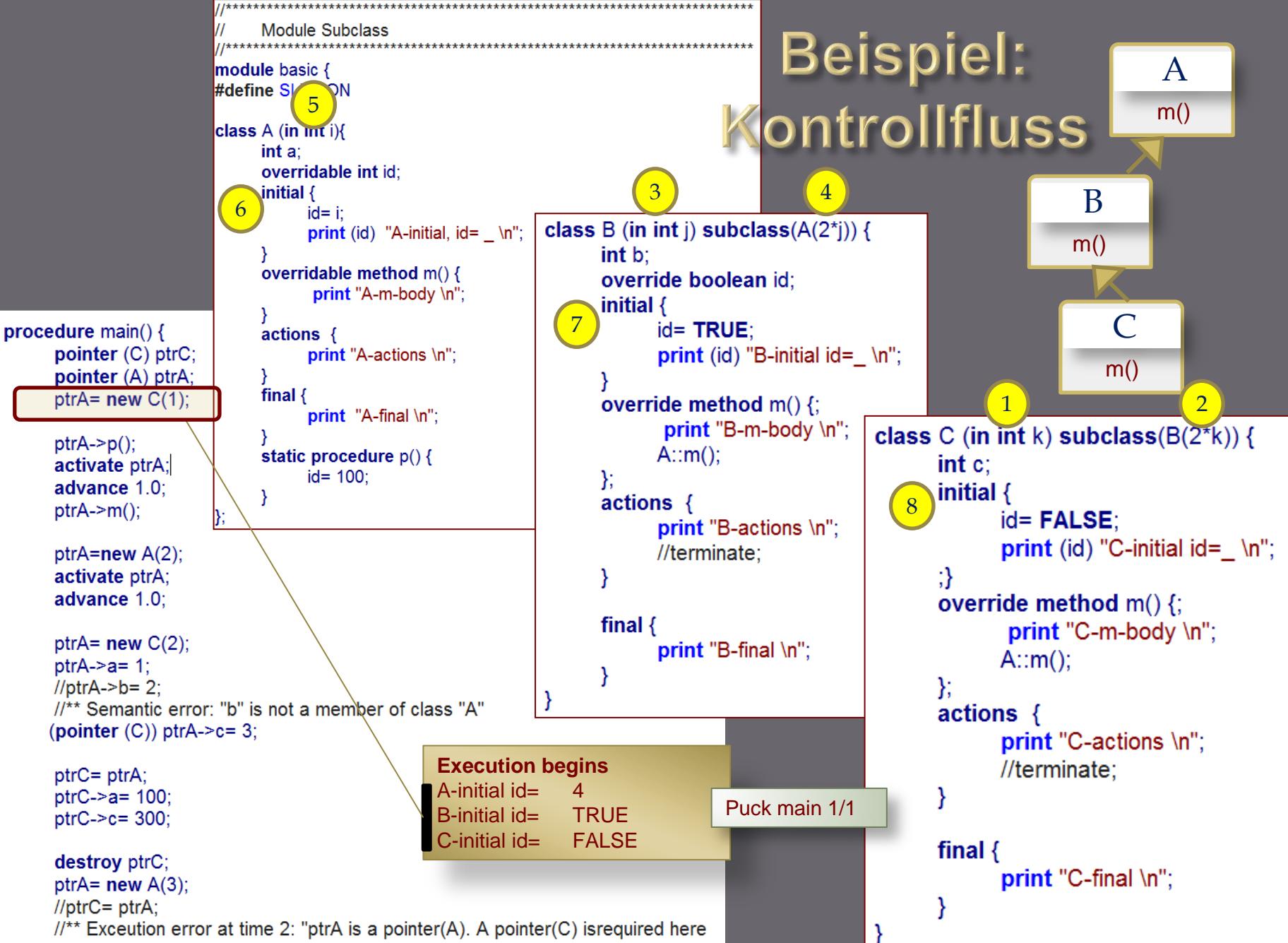


Aktionsreihenfolge für Objekte
abgeleiteter Klassen

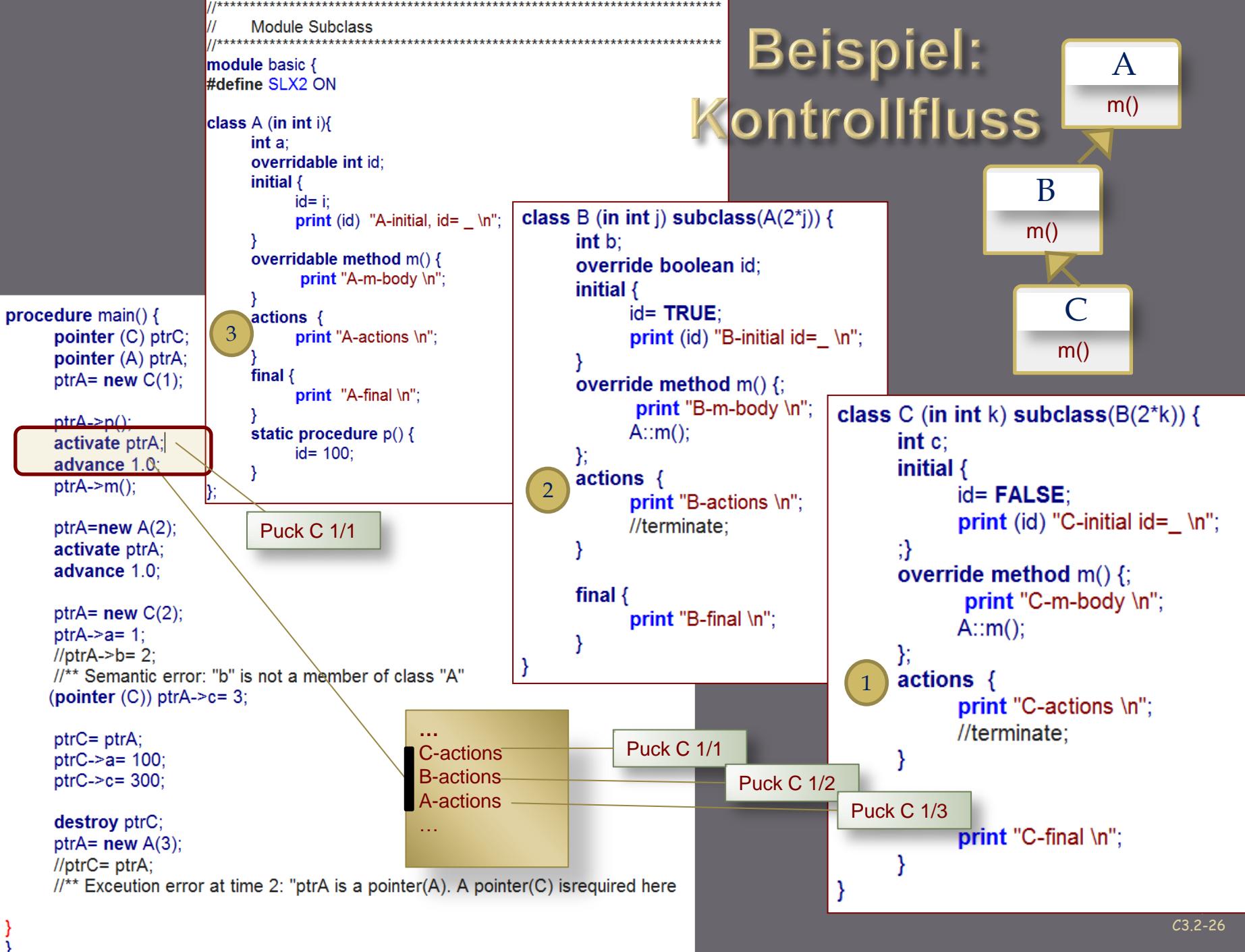


Regel: einmal overridable,
danach immer overridable

Beispiel: Kontrollfluss



Beispiel: Kontrollfluss



ACHTUNG

weitere Situation, die zur impliziten Generierung von Pucks führt

1. bislang bekannt

- main-Start
- **activate** *classId-objectNr-1*
- **fork** *classId-objectNr-n*

2. hinzu kommt

- bei Ausführung einer Action-Property wird zu Beginn ein Child-Puck für die Action-Property der (falls vorhanden) nächsten Basisklasse generiert

Bem.-1: u.U. muss bei Bedarf der nutzerdefinierte Puck-Pointer „`my_puck`“ zu Beginn jeder Action-Property einer Vererbungskette neu gesetzt werden:

`my_puck= ACTIVE;`

Bem.-2: Puckfreigabe erfolgt bei Beendigung der zu steuernden Action-Property
(Bedingung: kein nutzerdefinierter Zeiger zeigt noch auf den Puck)

Beispiel: Kontrollfluss

```

//***** Module Subclass *****
//***** SLX2 ON *****
module basic {
    class A (in int i){
        int a;
        overridable int id;
        initial {
            id= i;
            print (id) "A-initial, id=_\n";
        }
        overridable method m() {
            print "A-m-body\n";
        }
        actions {
            print "A-actions\n";
        }
        final {
            print "A-final\n";
        }
        static procedure p() {
            id= 100;
        }
    }

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();

    ptrA=new A(2);
    activate ptrA;
    advance 1.0;

    ptrA= new C(2);
    ptrA->a= 1;
    //ptrA->b= 2;
    /** Semantic error: "b" is not a member of class "A"
    (pointer (C)) ptrA->c= 3;

    ptrC= ptrA;
    ptrC->a= 100;
    ptrC->c= 300;

    destroy ptrC;
    ptrA= new A(3);
    //ptrC= ptrA;
    /** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here
}

```

3

Puck C 1/1

...

C-m-body
A-m-body
...

```

class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id=_\n";
    }
    override method m() {
        print "B-m-body\n";
        A::m();
    }
    actions {
        print "B-actions\n";
        //terminate;
    }
    final {
        print "B-final\n";
    }
}

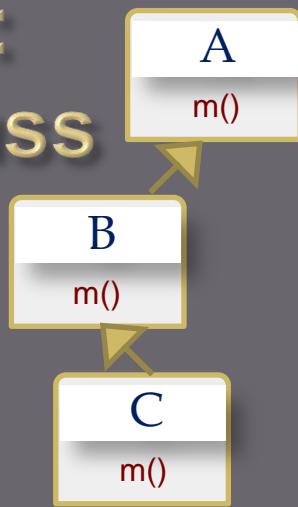
```

1
2

```

class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id=_\n";
    }
    override method m() {
        print "C-m-body\n";
        A::m();
    }
    actions {
        print "C-actions\n";
        //terminate;
    }
    final {
        print "C-final\n";
    }
}

```



Beispiel: Kontrollfluss

```

//***** Module Subclass *****
//***** SLX2 ON *****
module basic {
    class A (in int i) {
        int a;
        overridable int id;
        initial {
            id= i;
            print (id) "A-initial, id=_\n";
        }
        overridable method m() {
            print "A-m-body\n";
        }
        actions {
            print "A-actions\n";
        }
        final {
            print "A-final\n";
        }
        static procedure p() {
            id= 100;
        }
    }
}

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();
};

ptrA=new A(2);
activate ptrA;
advance 1.0;

ptrA= new C(2);
ptrA->a= 1;
//ptrA->b= 2;
/** Semantic error: "b" is not a member of class "A"
(pointer (C)) ptrA->c= 3;

ptrC= ptrA;
ptrC->a= 100;
ptrC->c= 300;

destroy ptrC;
ptrA= new A(3);
//ptrC= ptrA;
/** Execution error at time 2: "ptrA is a po
}

```

Puck main 1/1

...

A-initial, id= 2
 C-final
 B-final
 A-final

```

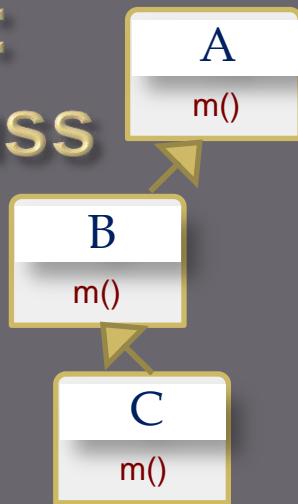
class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id=_\n";
    }
    override method m() {
        print "B-m-body\n";
        A::m();
    }
    actions {
        print "B-actions\n";
        //terminate;
    }
    final {
        print "B-final\n";
    }
}

```

```

class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id=_\n";
    }
    override method m() {
        print "C-m-body\n";
        A::m();
    }
    actions {
        print "C-actions\n";
        //terminate;
    }
    final {
        print "C-final\n";
    }
}

```



Beispiel: Kontrollfluss

```

//***** Module Subclass *****
//***** Module Subclass *****
module basic {
#define SLX2 ON

class A (in int i) {
    int a;
    overridable int id;
    initial {
        id= i;
        print (id) "A-initial, id=_\n";
    }
    overridable method m() {
        print "A-m-body\n";
    }
    actions {
        print "A-actions\n";
    }
    final {
        print "A-final\n";
    }
    static procedure p() {
        id= 100;
    }
}

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();

    ptrA=new A(2);
    activate ptrA;
    advance 1.0;

    ptrA= new C(2);
    ptrA->a= 1;
    //ptrA->b= 2;
    /** Semantic error: "b" is not a member of class "A"
    (pointer (C)) ptrA->c= 3;

    ptrC= ptrA;
    ptrC->a= 100;
    ptrC->c= 300;

    destroy ptrC;
    ptrA= new A(3);
    //ptrC= ptrA;
    /** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here
}

```

Puck A 1/1

A-actions

```

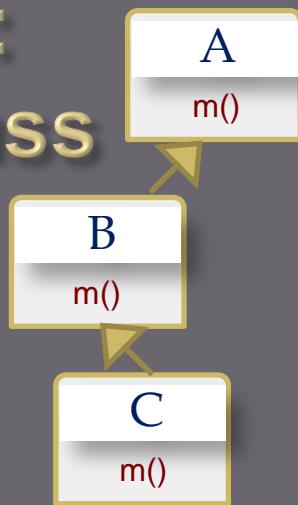
class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id=_\n";
    }
    override method m() {
        print "B-m-body\n";
        A::m();
    }
    actions {
        print "B-actions\n";
        //terminate;
    }
    final {
        print "B-final\n";
    }
}

```

```

class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id=_\n";
    }
    override method m() {
        print "C-m-body\n";
        A::m();
    }
    actions {
        print "C-actions\n";
        //terminate;
    }
    final {
        print "C-final\n";
    }
}

```



Beispiel: Kontrollfluss

```

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();

    ptrA=new A(2);
    activate ptrA;
    advance 1.0;
}

```

ptrA= new C(2);

ptrA->a= 1;
//ptrA->b= 2;
/ Semantic error: "b" is not a member of class "A"**
(pointer (C)) ptrA->c= 3;

```

ptrC= ptrA;
ptrC->a= 100;
ptrC->c= 300;

```

```

destroy ptrC;
ptrA= new A(3);
//ptrC= ptrA;

```

/** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here

```

//***** Module Subclass *****
module basic {
#define SLX2 ON

class A (in int i){
    int a;
    overridable int id;
    initial {
        id= i;
        print (id) "A-initial, id= _ \n";
    }
    overridable method m() {
        print "A-m-body \n";
    }
    actions {
        print "A-actions \n";
    }
    final {
        print "A-final \n";
    }
    static procedure p() {
        id= 100;
    }
}

```

```

class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id= _ \n";
    }
    override method m() {
        print "B-m-body \n";
        A::m();
    }
    actions {
        print "B-actions \n";
        //terminate;
    }
    final {
        print "B-final \n";
    }
}

```

```

class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id= _ \n";
    }
    override method m() {
        print "C-m-body \n";
        A::m();
    }
    actions {
        print "C-actions \n";
        //terminate;
    }
    final {
        print "C-final \n";
    }
}

```

Puck main 1/1

...

| | |
|---------------|---|
| A-initial id= | 8 |
| B-initial id= | 8 |
| C-initial id= | 8 |
| ... | |



Beispiel: Kontrollfluss

```

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();
}

```

```

ptrA=new A(2);
activate ptrA;
advance 1.0;

```

```

ptrA= new C(2);
ptrA->a= 1;
//ptrA->b= 2;
/** Semantic error: "b" is not a member of class "A"
(pointer (C)) ptrA->c= 3;

```

```

ptrC= ptrA;
ptrC->a= 100;
ptrC->c= 300;

```

```

destroy ptrC;
ptrA= new A(3);
//ptrC= ptrA;
/** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here
}

```

Puck main 1/1

...

Freigabe vom A-Objekt
...Korrekte und fehlerhafte
Attribut-Zugriffe

```

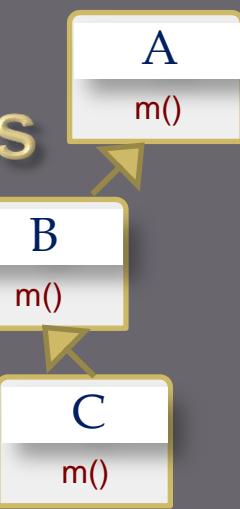
class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id=_ \n";
    }
    override method m() {
        print "B-m-body \n";
        A::m();
    };
    actions {
        print "B-actions \n";
        //terminate;
    }
    final {
        print "B-final \n";
    }
}

```

```

class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id=_ \n";
    }
    override method m() {
        print "C-m-body \n";
        A::m();
    };
    actions {
        print "C-actions \n";
        //terminate;
    }
    final {
        print "C-final \n";
    }
}

```



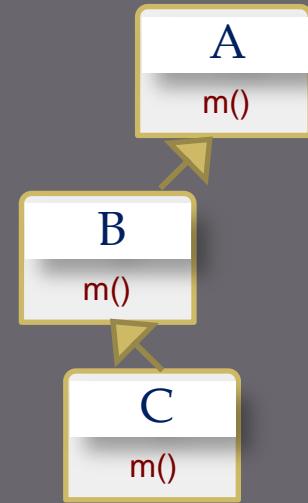
Cast-Operator

```
ptrC= (pointer (C)) ptraA;
```

```
procedure main() {  
    pointer (C) ptrC;  
    pointer (A) ptraA;  
    ptraA= new C(1);  
  
    ptraA->p();  
    activate ptraA;  
    advance 1.0;  
    ptraA->m();  
  
    ptraA=new A(2);  
    activate ptraA;  
    advance 1.0;  
  
    ptraA= new C(2);  
    ptraA->a= 1;  
    //ptrA->b= 2;  
    /** Semantic error: "b" is not a member of class "A"  
    (pointer (C)) ptraA->c= 3;
```

```
ptrC= ptraA;  
ptrC->a= 100;  
ptrC->c= 300;
```

```
destroy ptrC;  
ptrA= new A(3);  
//ptrC= ptraA;  
/** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here
```



Cast-Operator

- erforderlich, falls per „ptrA“ auf echte Attribute/Methoden von B und C zugegriffen werden soll

Beispiel: Kontrollfluss

```

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();
}

```

```

ptrA=new A(2);
activate ptrA;
advance 1.0;

```

```

ptrA= new C(2);
ptrA->a= 1;
//ptrA->b= 2;
/** Semantic error: "b" is not a member of class "A"
(pointer (C)) ptrA->c= 3;

```

```

ptrC= ptrA;
ptrC->a= 100;
ptrC->c= 300;

```

```

destroy ptrC;
ptrA= new A(3);
//ptrC= ptrA;

```

/** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here

Puck main 1/1

Kopie des Zeigerwertes
für einen Zeiger, der statisch mit
der Klasse C qualifiziert ist

```

//***** Module Subclass *****
module basic {
#define SLX2 ON

class A (in int i){
    int a;
    overridable int id;
    initial {
        id= i;
        print (id) "A-initial, id= _ \n";
    }
    overridable method m() {
        print "A-m-body \n";
    }
    actions {
        print "A-actions \n";
    }
    final {
        print "A-final \n";
    }
    static procedure p() {
        id= 100;
    }
}

```

```

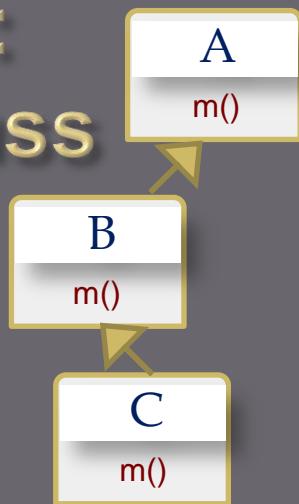
class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id= _ \n";
    }
    override method m() {
        print "B-m-body \n";
        A::m();
    }
    actions {
        print "B-actions \n";
        //terminate;
    }
    final {
        print "B-final \n";
    }
}

```

```

class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id= _ \n";
    }
    override method m() {
        print "C-m-body \n";
        A::m();
    }
    actions {
        print "C-actions \n";
        //terminate;
    }
    final {
        print "C-final \n";
    }
}

```



Beispiel: Kontrollfluss

```
procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();

    };

```

```
ptrA=new A(2);
activate ptrA;
advance 1.0;
```

```
ptrA= new C(2);
ptrA->a= 1;
//ptrA->b= 2;
/** Semantic error: "b" is not a member of class "A"
(pointer (C)) ptrA->c= 3;
```

```
ptrC= ptrA;
ptrC->a= 100;
ptrC->c= 300;
```

```
destroy ptrC;
ptrA= new A(3);
//ptrC= ptrA;
/** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here
```

```
/*
// Module Subclass
*/
module basic {
#define SLX2 ON

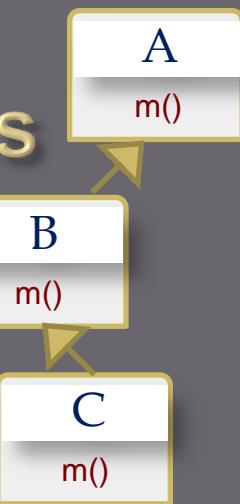
class A (in int i){
    int a;
    overridable int id;
    initial {
        id= i;
        print (id) "A-initial, id= _ \n";
    }
    overridable method m() {
        print "A-m-body \n";
    }
    actions {
        print "A-actions \n";
    }
    final {
        print "A-final \n";
    }
    static procedure p() {
        id= 100;
    }
}
```

```
class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id= _ \n";
    }
    override method m() {
        print "B-m-body \n";
        A::m();
    }
    actions {
        print "B-actions \n";
        //terminate;
    }
    final {
        print "B-final \n";
    }
}
```

```
class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id= _ \n";
    }
    override method m() {
        print "C-m-body \n";
        A::m();
    }
    actions {
        print "C-actions \n";
        //terminate;
    }
    final {
        print "C-final \n";
    }
}
```

Puck main 1/1

Unproblematische
Attribut-Zugriffe



Beispiel: Kontrollfluss

```
procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();
}
```

```
ptrA=new A(2);
activate ptrA;
advance 1.0;
```

```
ptrA= new C(2);
ptrA->a= 1;
//ptrA->b= 2;
/** Semantic error: "b" is not a member of class "A"
(pointer (C)) ptrA->c= 3;
```

```
ptrC= ptrA;
ptrC->a= 100;
ptrC->c= 300;
```

```
destroy ptrC;
ptrA= new A(3);
//ptrC= ptrA;
/** Execution error at time 2: "ptrA is a po
```

Puck main 1/1

...

C-final
B-final
A-final
...

```
class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id=_ \n";
    }
    override method m() {
        print "B-m-body \n";
        A::m();
    };
    actions {
        print "B-actions \n";
        //terminate;
    }
    final {
        print "B-final \n";
    }
}
```

```
class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id=_ \n";
    }
    override method m() {
        print "C-m-body \n";
        A::m();
    };
    actions {
        print "C-actions \n";
        //terminate;
    }
    final {
        print "C-final \n";
    }
}
```



Beispiel: Kontrollfluss

```

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();
}

```

```

ptrA=new A(2);
activate ptrA;
advance 1.0;

```

```

ptrA= new C(2);
ptrA->a= 1;
//ptrA->b= 2;
/** Semantic error: "b" is not a member of class "A"
(pointer (C)) ptrA->c= 3;

```

```

ptrC= ptrA;
ptrC->a= 100;
ptrC->c= 300;

```

```

destroy ptrC;
ptrA= new A(3);

```

//ptrC= ptrA;
/** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here

```

//***** Module Subclass *****
module basic {
#define SLX2 ON

class A (in int i){
    int a;
    overridable int id;
    initial {
        id= i;
        print (id) "A-initial, id= _ \n";
    }
    overridable method m() {
        print "A-m-body \n";
    }
    actions {
        print "A-actions \n";
    }
    final {
        print "A-final \n";
    }
    static procedure p() {
        id= 100;
    }
}

```

```

class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id= _ \n";
    }
    override method m() {
        print "B-m-body \n";
        A::m();
    }
    actions {
        print "B-actions \n";
        //terminate;
    }
    final {
        print "B-final \n";
    }
}

```

```

class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id= _ \n";
    }
    override method m() {
        print "C-m-body \n";
        A::m();
    }
    actions {
        print "C-actions \n";
        //terminate;
    }
    final {
        print "C-final \n";
    }
}

```

Puck main 1/1

...
A-initial id= 3



Beispiel: Kontrollfluss

```

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();
}

```

```

ptrA=new A(2);
activate ptrA;
advance 1.0;

```

```

ptrA= new C(2);
ptrA->a= 1;
//ptrA->b= 2;
/** Semantic error: "b" is not a member of class "A"
(pointer (C)) ptrA->c= 3;

```

```

ptrC= ptrA;
ptrC->a= 100;
ptrC->c= 300;

```

```

destroy ptrC;
ptrA= new A(3);

```

//ptrC= ptrA,
/** Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here

Puck main 1/1

Laufzeitfehler

```

//***** Module Subclass *****
module basic {
#define SLX2 ON

class A (in int i){
    int a;
    overridable int id;
    initial {
        id= i;
        print (id) "A-initial, id= _ \n";
    }
    overridable method m() {
        print "A-m-body \n";
    }
    actions {
        print "A-actions \n";
    }
    final {
        print "A-final \n";
    }
    static procedure p() {
        id= 100;
    }
}

```

```

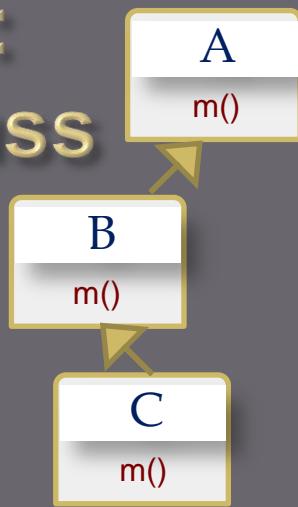
class B (in int j) subclass(A(2*j)) {
    int b;
    override boolean id;
    initial {
        id= TRUE;
        print (id) "B-initial id= _ \n";
    }
    override method m() {
        print "B-m-body \n";
        A::m();
    }
    actions {
        print "B-actions \n";
        //terminate;
    }
    final {
        print "B-final \n";
    }
}

```

```

class C (in int k) subclass(B(2*k)) {
    int c;
    initial {
        id= FALSE;
        print (id) "C-initial id= _ \n";
    }
    override method m() {
        print "C-m-body \n";
        A::m();
    }
    actions {
        print "C-actions \n";
        //terminate;
    }
    final {
        print "C-final \n";
    }
}

```



Beispiel: Kontrollfluss

A
m()

B
m()

```

procedure main() {
    pointer (C) ptrC;
    pointer (A) ptrA;
    ptrA= new C(1);

    ptrA->p();
    activate ptrA;
    advance 1.0;
    ptrA->m();

    ptrA=new A(2);
    activate ptrA;
    advance 1.0;

    ptrA= new C(2);
    ptrA->a= 1;
    //ptrA->b= 2;
    /* Semantic error: "b" is not a member of
    (pointer (C)) ptrA->c= 3;

    ptrC= ptrA;
    ptrC->a= 100;
    ptrC->c= 300;

    destroy ptrC;
    ptrA= new A(3);
    //ptrC= ptrA;
    /* Execution error at time 2: "ptrA is a pointer(A). A pointer(C) is required here
}

```

Puck main 1/1

Subclass.rtf: SLX-64 UL211 Lines: 1,841 Errors: 0 Warnings: 0 Lines/Second: 306,133 Memory: 2 MB
Execution begins
A-initial, id= 4
B-initial id=TRUE
C-initial id=FALSE
C-actions
B-actions
A-actions
C-m-body
A-m-body
A-initial, id= 2
C-final
B-final
A-final
A-actions
A-initial, id= 8
B-initial id=TRUE
C-initial id=FALSE
A-final
A-initial, id= 3
C-final
B-final
A-final

Execution complete

Objects created: 7 passive and 5 active Pucks created: 6 Memory: 2 MB Time: 0.06 seconds

```

        print "C-final \n";
    }
}

```

Statischer und dynamischer Typetest

```
class A {  
    int i;  
}  
  
class B subclass(A) {  
    int j;  
}  
  
procedure main() {  
    pointer(A) a = new B();  
  
    set(A) as;  
    place new B() into as;  
}
```

```
class A {  
}  
  
class B (int l) subclass(A) {  
    int k = l;  
}  
  
procedure main() {  
    pointer(A) a = new B(1);  
    pointer(B) b = a; // OK: checked at run-time  
    pointer(B) bb = new A(); // ERROR  
}
```

polymorphe Liste

- kann sowohl A-Objekte
- als auch Objekte von direkten oder indirekten Ableitungen enthalten

Cast-Operator

- erforderlich, falls per „a“ auf echte Attribute von B zugegriffen werden soll
- nicht notwendig, falls per „b“ auf Attribute von A und B zugegriffen werden soll

Prozedur = Methode

```
class C {  
    method m() {  
        ...  
    }  
}
```

Klassenspezifische (nutzereigene) Prozeduren,
die über Objekte der Klasse operieren
(impliziter Vermittlung des **ME**-Operators)

Vererbung und (virtuelle) Methoden

- Klassen in **SLX 1.x** besitzen keine Methoden, nur **Properties** (als vordefinierte parameterlose Methoden)
- Klassen in **SLX 2.x** besitzen darüber hinaus nutzerdefinierte Methoden,

```
class C {  
    method m() {  
        ...  
    }  
}
```

Klassenspezifische (nutzereigene) Prozeduren,
die über Objekte der Klasse operieren
(impliziter Vermittlung des **ME**-Operators)

- diese können **virtuell** sein und in Ableitungen **redefiniert** werden

```
class vehicle {  
    overridable method GetVehiclePosition(out double x, out double y) {...}  
};  
  
class tractor subclass(vehicle) {  
    override method GetVehiclePosition(out double x, out double y, ...,  
}
```

identische Signatur
ist zwingend

- **Regel:** einmal virtuell immer virtuell