

# Algorithms and Data Structures

## (Abstract) Data Types

Ulf Leser

# Content of this Lecture

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- Example
- Abstract Data Types
- Two important Examples: Stacks and Queues

# Problem

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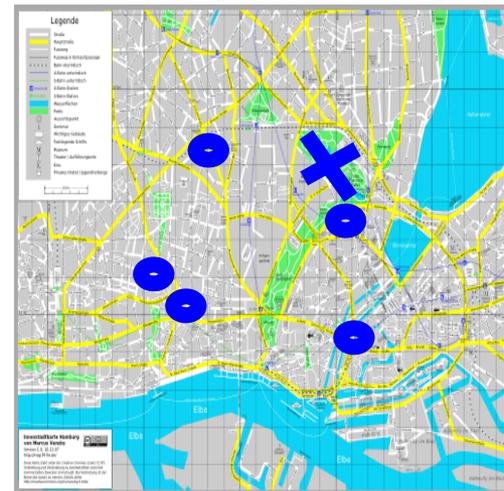
- Suppose you are in the centre of Hamburg and are **looking for the next (i.e., closest)** laptop repair shop
- Fortunately, your mobile knows your position and has a list of laptop repair shops in Hamburg
- How does your mobile find the **closest shop**?

# Classical Post Box Problem

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- Suppose a city with  $n$  boxes located at arbitrary positions
- You wake up in the middle of the city with a letter in your hand; the letter should be thrown in the closest post box
- How do you find the closest post box?
  - You have a list with locations of all post boxes
- Looking at a map is not the answer
- Devise an algorithm

```
S: set_of_coordinates;  
c: coordinate (x,y)  
...
```



# Simple Solution

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```
Input
  S: set_of_coordinates;
  c: coordinate (x,y);    # your loc
t: coordinate;           # closest box
m: real := MAXREAL;      # smal. dist
for each c'∈S do
  if m > distance(c,c') then
    m := distance(c,c');
    t := c';
  end if;
end for;
return t;
```

- How much work?

# Simple Solution

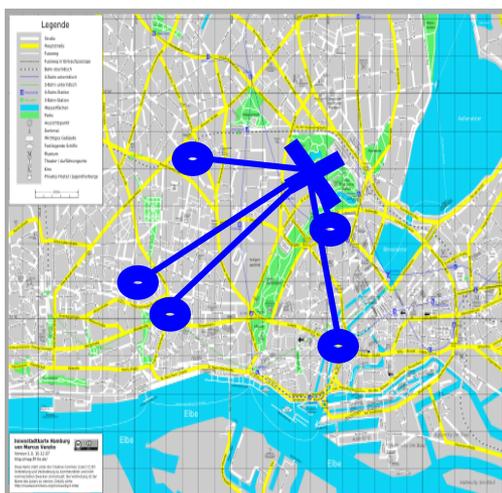
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```
Input
  S: set_of_coordinates;
  c: coordinate (x,y);      # your loc
t: coordinate;              # closest box
m: real := MAXREAL;        # smal. dist
for each c'∈S do
  if m > distance(c,c') then
    m := distance(c,c');
    t := c';
  end if;
end for;
return t;
```

- Clearly, we can save the second call to “distance”
- Thus, we need to compute  $|S|$  distances, make  $|S|$  comparisons, and perform at most  $2*|S|$  assignments
- Together: We perform  $O(|S|)$  operations, which are either in  $O(1)$  or distance computations

# Simple Solution

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- We compute  $|S|$  distances ...
- **Euclidian distance**
  - In 2D: 6 arithmetic ops

$$\text{dist}((x_1, y_1), (x_2, y_2)) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

# Not the only Option



- We compute  $|S|$  distances
- ...
- **Manhattan distance**
  - 5 basic operations

$$\text{dist}((x_1, y_1), (x_2, y_2)) = |x_1 - x_2| + |y_1 - y_2|$$

# Complexity



- We compute  $|S|$  distances
- ...
- Both cases:  $O(|S| * \text{dim}(S))$ 
  - $\text{dim}(S)$ : Number of dimensions of points in  $S$
  - If  $\text{dim}(S)=k$  and considered a constant:  $O(|S|)$

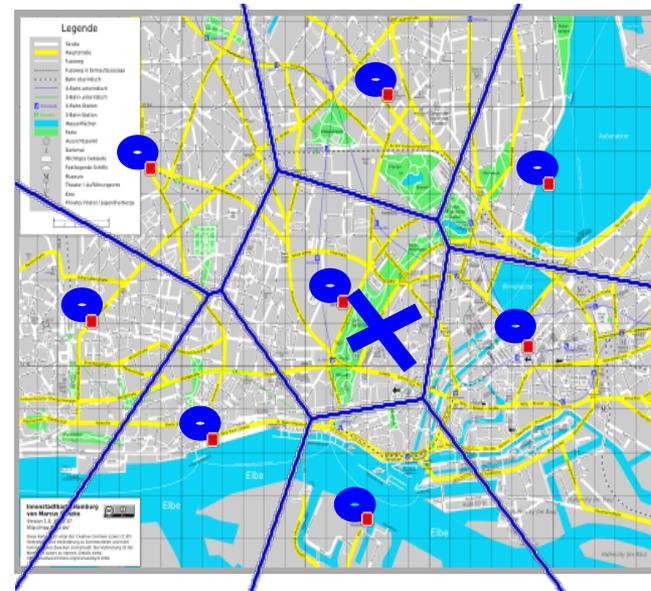
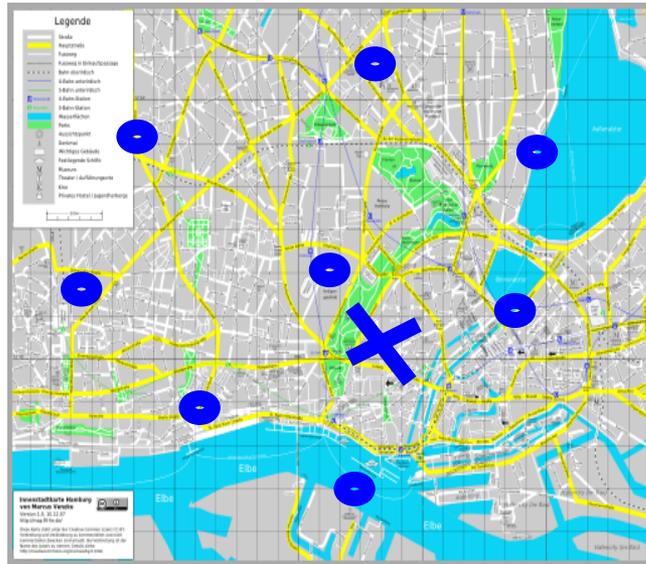
# Data Structure Point of View

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```
input
  S: set_of_coordinates;
  c: coordinate (x,y);
t: coordinate;
m: real := MAXREAL;
For each c'∈S do
  if m > dist(c,c') then
    m := dist(c,c');
    t := c';
  end if;
end for;
return t;
```

- Data structures
  - We need a **set S of 2D-coordinates**
  - For NN-search, the algorithm must iterate over the elements of this set in any order
- Now assume we need to perform such **searches very often**
  - Can we represent S in **another way (S')**, such that searching requires less work?
  - Note: Time for **computing S' from S will be ignored**
    - Perform before searching starts
    - Assuming that S does not change

# Voronoi Diagrams



- **Pre-processing:** Compute for every point  $s \in S$  its **Voronoi area**, i.e., the area in which all points have  $s$  as **nearest point** from  $S$ 
  - Can be achieved in  $O(|S| \cdot \log(|S|))$  time (no details here)
- Nearest-neighbor search using Voronoi diagrams is  $O(\log(|S|))$
- Conclusion: Finding a **proper data structure** does pay off

# Data Structures and Data Types

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- A **data structure** is a computational representation of elementary objects
  - An array, a linked list, a matrix, a tree, a graph, ....
- A combination of **data structure and operations** on this structure is called a **data type**
  - “Operations”: Application programming interface (API)
  - If we ignore implementation: **Abstract data type**
    - Also called signature
    - No complexity analysis, but correctness proofs
  - With concrete implementation: **Physical data type**
    - Software libraries
- ADT: Like a class in Java, i.e. variables and interface

# Searching Shops

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- We want a **piece of software T** that ...
- T must store data
  - Set of coordinates (data structure)
- T must support (at least) two **operations**
  - T.init (S: set\_of\_coordinates)
  - T.nearestNeighbor(c: coordinate): coordinate
  - T apparently uses **another data structure**: "coordinate"
- T **could** have many more operations
  - T.insert(c: coordinate)
  - T.delete(c: coordinate)
  - T.print()
  - ...

# Content of this Lecture

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- Example
- Abstract Data Types
- Two important Examples: Stacks and Queues

# Abstract Data Types (ADT)

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- An ADT defines a **set of operations** over a **set of objects** of a certain (more basic) type
  - Or over **multiple sets** of objects of different or same types
- An ADT is **independent of an implementation**
  - Different physical means to represent the objects
  - Different algorithms to implement the operations
- Typical requirement: **Encapsulation**
  - Objects are accessed only through the operations

# Example ADT

---

```
type points
import
  coordinate;
operators
  add:          points x coordinate → points;
  n_neighbor:  points x coordinate → coordinate;
```

- ADT that we could use for our app for searching shops
- Defines **two operations**
  - A way to insert shops (with their coordinates)
  - A way to get the nearest shop with respect to a given coordinate
- Assumes a data type “coordinate” to be given
  - We always assume basic data types to be given: Int, real, string,...
- Not the only way

# Modeling More Details

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```
type shop
import
  coordinate;
operators
  getName: shop → string;
  getCoor: shop → coordinate;
```

```
type shops
import
  shop;
operators
  add:          shops x shop → shops;
  n_neighborC: shops x coordinate → coordinate;
  n_neighborN: shops x coordinate → string;
  n_neighborS: shops x coordinate → shop;
```

- An ADT defines **what is necessary and convenient**
- Specifying an ADT is a **design process**
  - Shop owner? Laptop models being repaired? Opening hours?
  - Depends on requirements, ease-of-use, extensibility, personal preferences, existing ADTs, ...
  - See lectures on **Software Engineering**

# Reusing Existing ADTs

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- For implementing shops, it would be helpful to **reuse something** that can manage a set of objects
- We **need a set** – an ADT in itself
  - A **parameterized ADT**– a set of elements of **arbitrary type T**
  - For our ADT **points**, T will manage objects of type **coordinate**

```
type set(T)
import
  integer, bool;
operators
  isEmpty: set → bool;
  add:     set x T → set;
  delete:  set x T → set;
  contains: set x T → bool;
  size:    set → integer;
```

A data type – not a variable

# Reusing Existing ADTs

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- For implementing shops, it would be helpful to reuse something that can manage a set of objects
- We need a set – an ADT in itself
  - A parameterized ADT– a set of elements of arbitrary type T
  - For our ADT `points`, T will manage objects of type `coordinate`

```
type set( T)
import
  integer, bool;
operators
  isEmpty:  set → bool;
  add:      set x T → set;
  delete:   set x T → set;
  contains: set x T → bool;
  size:     set → integer;
  ...
```

Java interface SET  
has ~20 operations

# Axioms: What we know about an ADT

---

- We expect operations on sets to have a **certain semantic**
  - Adding an element increases size by one
  - If a set is empty, its length is 0
  - ...
- These can be encoded as **axioms**: Conditions that **must always hold**
  - Defined as logical formulas
  - Also called **invariants**

```
type set( T)
import
operators
  isEmpty:  set → bool;
  add:      set x T → set;
  contains: set x T → bool;
  delete:   set x T → set;
  length:   set → integer;
axioms:  $\forall f: \text{set}, \forall t: T$ 
  size(add(f,t)) = size(f) + 1;
  size(f)=0  $\Leftrightarrow$  isEmpty(f);
  ...
```

# Axioms: What we know about an ADT

---

- We expect operations on sets to have a certain semantic
  - Adding an element increases size by one
  - If a set is empty, its length is 0
  - ...
- These can be encoded as axioms: Conditions that must always hold
  - Defined as logical formulas
  - Also called invariants
- **But stop!** Where is the error!

```
type set( T)
import
operators
  isEmpty:  set → bool;
  add:      set x T → set;
  contains: set x T → bool;
  delete:   set x T → set;
  length:   set → integer;
axioms: ∀ f: set, ∀ t: T
  size(add(f,t)) = size(f) + 1;
  size(f)=0 ⇔ isEmpty(f);
...
```

# Axioms: What we know about an ADT

---

- We expect operations on sets to have a certain semantic
  - Adding an element increases size by one **if not a duplicate**
  - If a set is empty, its length is 0
  - ...
- These can be encoded as axioms: Conditions that must always hold
  - Defined as logical formulas
  - Also called invariants

```
type set( T)
import
operators
  isEmpty:  set → bool;
  add:      set x T → set;
  contains: set x T → bool;
  delete:   set x T → set;
  length:   set → integer;
axioms: ∀ f: set, ∀ t: T
  if contains(f,t) then
    ERROR;
  else
    size(add(f,t)) = size(f) + 1;
  size(f)=0 ⇔ isEmpty(f);
  ...
```

# Set versus Points

---

```
type points
import
  coordinate, set(coordinate);
Operators
  add:      points x coordinate → points;
           # Can be implemented as set.add
  neighbor: points x coordinate → coordinate;
           # Not implemented in set!
axioms
  neighbor(p,c) = {x | contains(p,x) ∧ ∀x' : contains(p, x') =>
                    distance(x,c) ≤ distance(x',c)};
```

- `points` can build on a set, but must add further operations
- But there is a problem ... which one?
  - What happens if **multiple x have the same distance** to c?

# Set versus Points

---

```
type points
import
  coordinate, set(coordinate);
Operators
  add:      points x coordinate → points;
  neighbor: points x coordinate → points;
axioms
  neighbor(p,c) = {x | contains(p,x) ∧ ∀x' : contains(p,x') :
                    distance(x,c) ≤ distance(x',c)};
```

# Content of this Lecture

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- Data Structures Again
- Abstract Data Types
- Two important examples: Stacks and Queues

# Sets and Lists

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- We looked at data types (points, shops) which essentially are sets
  - Canonical operations: add, contains, delete, size, ...
  - And **special operation**: nearestNeighbor
- A related **ADT is list**
  - In a list, elements are ordered (arbitrarily yet fixed)
  - Canonical operations: **addAt**, contains, **deleteAt**, length, ...
  - Different behavior (axioms)
    - **Duplicates** are no problem (same object at different positions)
    - No insertion after list end
    - ...

# One Take Home Message

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- This lecture will be **obsessed with lists** and sets
- Why?
  - There are **things**
  - ... and there a **lists of things**
- In CS, we need lists everywhere
  - Basis of every non-trivial algorithm
  - Investing effort in getting them efficient pays off in many many applications

# Stacks and Queues

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- Two related ADTs are of exceptional importance in computer science: **Stacks and Queues**
  - Both support mostly two operations
    - No contains, length, addAt, deleteAt, ...
  - These suffice for surprisingly many problems and applications
  - Both ADTs can be **implemented very efficiently**
    - More efficiently than sets or lists

# Queues

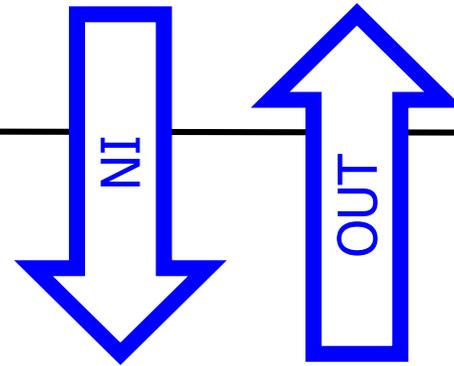
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- Two operations: Enqueue, dequeue
  - No access to objects of the list except the “head”
- Special semantic: First in, first out (FIFO)
- Apps: Breadth-first traversal, shortest paths, BucketSort, ...

# Stacks

---



- Operations: push, pop
  - No access to objects of the list except the “top”
- Special semantic: Last in, first out (LIFO)
- Apps: Call stacks, backtracking, “Kellerautomaten”, ...

# As Abstract Data Types

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```
type stack( T)
import
operators
  isEmpty: stack → bool;
  push:    stack x T → stack;
  pop:     stack → stack;
  top:     stack → T;
```

```
type queue( T)
import
operators
  isEmpty: queue → bool;
  enqueue: queue x T → queue;
  dequeue: queue → queue;
  head:    queue → T;
```

- Where is the **difference**?

# Signature does not Suffice

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```
type a( T)
import
operators
  isEmpty: a → bool;
  add:     a x T → a;
  remove:  a → a;
  give:    a → T;
```

```
type a( T)
import
operators
  isEmpty: a → bool;
  add:     a x T → a;
  remove:  a → a;
  give:    a → T;
```

- Where is the difference?
- From the **signature alone**, there is no difference
- Yet – we expect a **different behavior**

# Defining the Difference

---

```
type stack( T)
import
operators
  isEmpty: stack → bool;
  push:    stack x T → stack;
  pop:     stack → stack;
  top:     stack → T;
axioms ∀ s:stack, ∀ t:T
  top( push( s, t)) = t;
  pop( push( s, t)) = s;
```

```
type queue( T)
import
operators
  isEmpty: queue → bool;
  enqueue: queue x T → queue;
  dequeue: queue → queue;
  head:    queue → T;
axioms ∀ q:queue, ∀ t:T
  head( enqueue( q, t)) =
    if isEmpty( q): t
    else head( q);
  dequeue( enqueue( q, t)) =
    if isEmpty( q): q
    else enqueue( dequeue( q), t);
```

# Sets, Lists, Stacks, Queues

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- Compared to sets
  - No contains
  - No duplicate checks before insertion
    - Much faster!
  - Typically no size
  - Additional behavior with push/pop
- Compared to lists
  - No contains, no order, no positions
    - Much faster!
  - Typically no size
  - Additional behavior with push/pop

# Summary

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- We very briefly sneaked into (abstract) data types
  - Formal syntax for specification, semantics of axioms in physical data types, concrete language for axioms, specialization hierarchies, formal correctness proofs, ...
  - See module on “Methoden und Modelle des Systementwurfs”
- An old dream: Provide only precise specification and let all **code be generated automatically**
  - Provide so many axioms that **all relevant behavior** is covered
  - Enables formal proofs of correctness
  - Relevant especially for **security-relevant domains**
    - E.g. embedded systems in cars, airplanes, ...
- Practically: Very time consuming, error prone, and hard to maintain

# For this Lecture

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- Algorithms take an input; input has a type; **this type may offer special operations**
  - Whose complexity depends on the physical implementation
- We rarely talk about the “data structure” aspect but about **implementation of operations**
  - Whose complexity also depend on complexity of operations on basic types
- As basic types, we assume Int, real, string
  - With operations add, multiply, compare, ...
  - We assume  $O(1)$  for all basic operations

# Exemplary Questions

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- What is an abstract data type, what is a physical data type?
- What are typical operations of a list? Of a stack?
- Imagine a class storing rectangles in a plane. We want to add and remove rectangles, test if there are any rectangles, and find all rectangles intersection of given one. Define the ADT. What could be possible axioms?